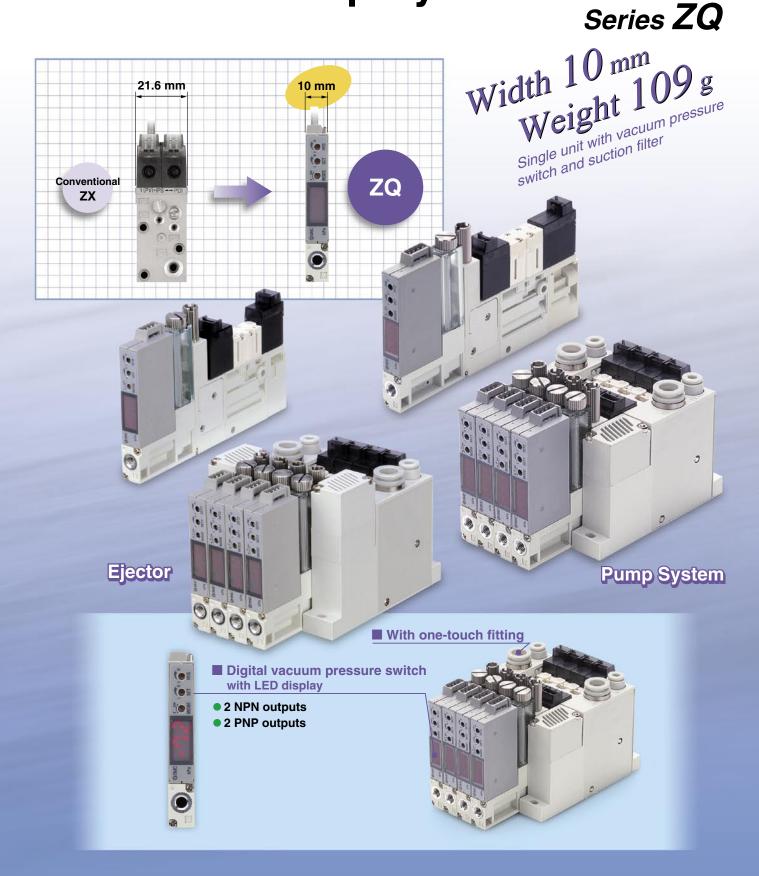
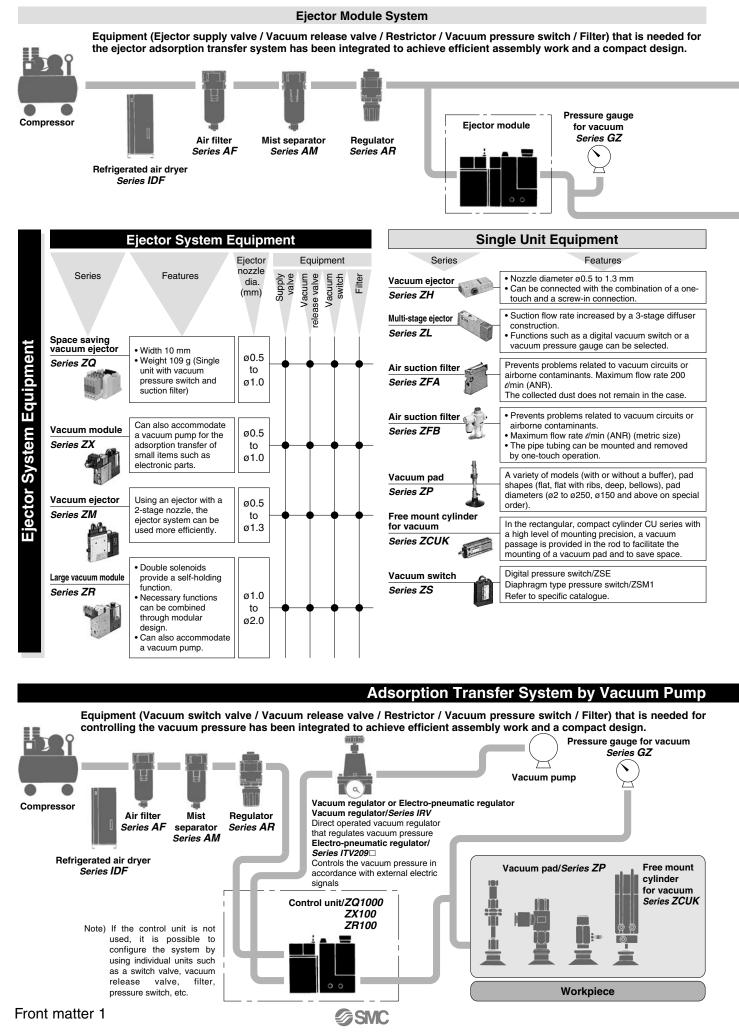


# Space Saving Vacuum Ejector & Vacuum Pump System

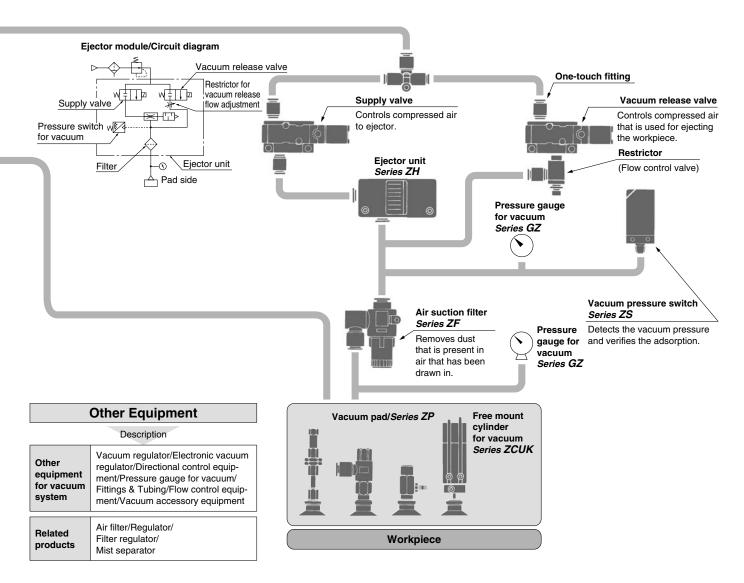


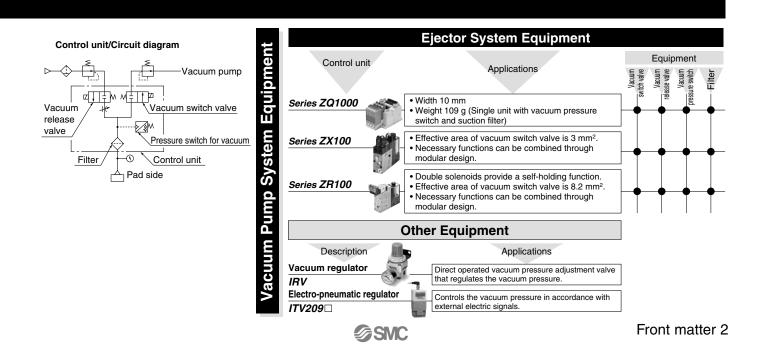
# Adsorption Transfer System by Ejector



#### **Single Unit System**

Equipment such as an ejector is configured as an individual unit. Thus, it is possible to create a flexible system configuration in which the circuit composition and the mounting locations can be selected as desired.





# Vacuum Equipment **Model Selection**

When an ejector and a vacuum pump are used for picking up a workpiece, the response times for picking up (and discharging), as well as the vacuum pressures during adsorption, vary according to the piping condition and the type of workpiece. Thus, by selecting the proper vacuum equipment, effective utilization of the vacuum system can be

# Vacuum Equipment Model Selection

# Selection Step

# 1. Pad selection

1-A Theoretical lifting force 1-B Calculation method: Pad diameter

# 2. Ejector / Vacuum switch valve selection

- 2-A Calculation method: Adsorption response time
- 2-B Leakage during workpiece adsorption
- 2-C Size of ejector and vacuum supply valve (with leakage)
- 2-D Size of ejector and vacuum supply valve (without leakage)

# Selection Step 1 Pad Selection

The pad diameter is found by means of a pad lift calculation.

The calculated value should be used for reference and confirmed by actual adsorption tests when necessary.

In the lift calculation, consideration should be given to the weight of the workpiece, forces due to acceleration during movement (lifting, stopping, turning, etc.) and a sufficient safety margin should be allowed.

An additional margin should also be allowed when determining the number and arrangement of pads.

# 1-A Theoretical Lifting Force

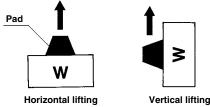
The theoretical lifting force of a pad can be found by calculation or from the theoretical lifting force table (1) shown below.

Calculation

 $W = P \times S \times 0.1 \times \frac{1}{t}$ 

- W: Lifting force (N)
- P: Vacuum pressure (kPa)
- S: Pad area (cm<sup>2</sup>)

t : Safety factor Horizontal lifting: 4 or more Vertical lifting: 8 or more



This type of application should basically be avoided.

## **Theoretical Lifting Force**

The theoretical lifting force (not including the safety factor) is found from the pad diameter and vacuum pressure. The required lifting force is then found by dividing the theoretical lifting force by the safety factor.

Lifting force = Theoretical lifting force ÷ t

(1) Theoretical Lifting Force (Theoretical lifting force = P x S x 0.1) Unit: N																
Pad size (mm)		2 x 4	3.5 x 7	4 x 10	ø <b>2</b>	ø <b>4</b>	ø <b>6</b>	ø <b>8</b>	ø <b>10</b>	ø13	ø16	ø <b>20</b>	ø <b>25</b>	ø <b>32</b>	ø <b>40</b>	ø <b>50</b>
Pad are	ea (cm²)	0.07	0.21	0.36	0.031	0.126	0.283	0.503	0.785	1.33	2.01	3.14	4.91	8.04	12.6	19.6
	-85	0.60	1.78	3.06	0.264	1.07	2.41	4.28	6.67	11.3	17.1	26.7	41.7	68.3	107	167
	-80	0.56	1.68	2.88	0.248	1.01	2.26	4.02	6.28	10.6	16.1	25.1	39.3	64.3	101	157
	-75	0.53	1.57	2.70	0.233	0.945	2.12	3.77	5.89	9.98	15.1	23.6	36.8	60.3	94.5	147
	-70	0.49	1.47	2.52	0.217	0.882	1.98	3.52	5.50	9.31	14.1	22.0	34.4	56.3	88.2	137
Vacuum pressure	-65	0.46	1.36	2.34	0.202	0.819	1.84	3.27	5.10	8.65	13.1	20.4	31.9	52.3	81.9	127
(kPa)	-60	0.42	1.26	2.16	0.186	0.756	1.70	3.02	4.71	7.98	12.1	18.8	29.5	48.2	75.6	118
(	-55	0.39	1.15	1.98	0.171	0.693	1.56	2.77	4.32	7.32	11.1	17.3	27.0	44.2	69.3	108
	-50	0.35	1.05	1.80	0.155	0.630	1.42	2.52	3.93	6.65	10.1	15.7	24.6	40.2	63.0	98.0
	-45	0.32	0.94	1.62	0.140	0.567	1.27	2.26	3.53	5.99	9.05	14.1	22.1	36.2	56.7	88.2
	-40	0.28	0.84	1.44	0.124	0.504	1.13	2.01	3.14	5.32	8.04	12.6	19.6	32.2	50.4	78.4

# Selection Step 1 Pad Selection

# 1-B Finding the Pad Diameter

A pad diameter which accounts for a safety factor based upon the workpiece lifting method (horizontal or vertical), can be selected by using the calculation formula or the selection graphs (Below graphs (1) and (2)).

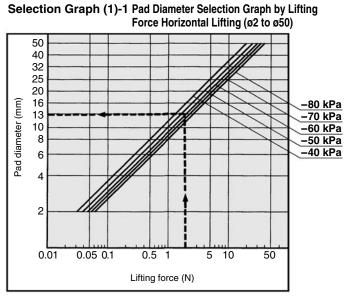
#### Calculation

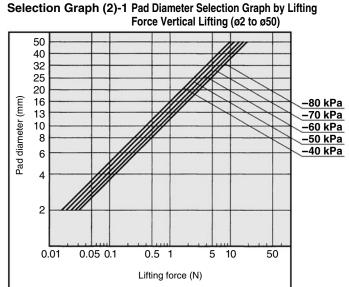
$$D = \sqrt{\frac{4}{3.14} \times \frac{1}{P} \times \frac{W}{n} \times t \times 1000}$$

- D : Pad diameter (mm) n : Number of pads per workpiece W: Lifting force (N)
- P: Vacuum pressure (kPa)
- t : Safety factor Horizontal lifting: 4 or more
  - Vertical lifting: 8 or more

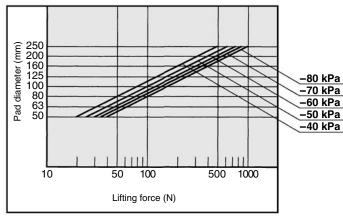
#### Selection Graph

After establishing the workpiece weight, number of pads to be used, and the vacuum pressure when adsorbing the workpiece, the pad diameters for horizontal lifting and vertical lifting can be found by means of using graphs (1) and (2).





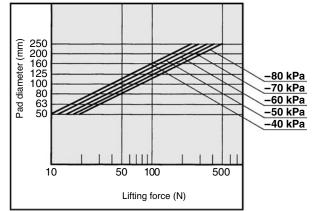
Selection Graph (1)-2 Pad Diameter Selection Graph by Lifting Force Horizontal Lifting (ø50 to ø250)



#### How to read the graph

Example: Workpiece weight 1 kg (Lifting force: 9.8 N) : Conditions/Number of pads: 5 pcs. Vacuum pressure –60 kPa Horizontal lifting

#### Selection Graph (2)-2 Pad Diameter Selection Graph by Lifting Force Vertical Lifting (ø50 to ø250)



#### <Selection procedure>

From the conditions at the left, the lifting force per pad: 9.8 N  $\div$  5 pcs. = 2 N, and for horizontal lifting, selection is made from graph (1)-1. Then, extending the intersection point of the lifting force 2 N and with a vacuum pressure of -60 kPa to the left, a pad diameter of 13 mm is obtained. Therefore, a pad diameter of 13 mm or greater should be selected.



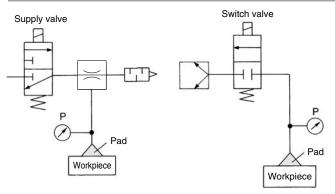
# Vacuum Equipment Model Selection

# Selection Step 2 Selection of Ejector and Vacuum Switch Valve

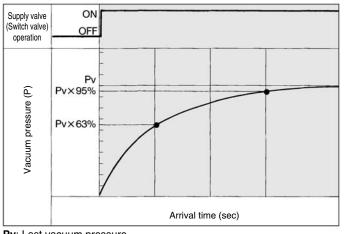
# 2-A Adsorption Response Time

When a pad is used for the adsorption transport of a workpiece, the approximate adsorption response time can be obtained (the length of time it takes for the pad's internal vacuum pressure to reach the pressure that is required for adsorption after the supply valve {vacuum switch valve} has been operated). An approximate adsorption response time can be obtained through formulas and selection graphs (3) and (4).

#### Vacuum System Circuit Diagram



#### Vacuum Pressure and Response Time after Supply Valve (switch valve) is Operated.



Pv: Last vacuum pressure

T1 : Arrival time to 63% of last vacuum pressure Pv

T2: Arrival time to 95% of last vacuum pressure Pv

## Calculation

Adsorption response times T1 and T2 can be obtained through the formulas given below.

Adsorption response time T<sub>1</sub>

$$=\frac{V \times 60}{Q}$$

Adsorption response time T<sub>2</sub> = 3 x T1

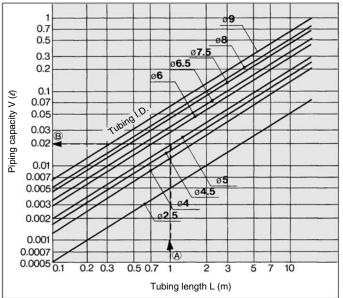
Piping capacity V  $=\frac{3.14}{4}D^{2} \times L \times \frac{1}{1000} (\ell)$ 

- T1: Arrival time to 63% of last
- vacuum pressure Pv (sec) T2 : Arrival time to 95% of last
  - vacuum pressure Pv (sec)
- D: Piping diameter (mm) L : Length from ejector and switch valve to pad (m)
- V : Piping capacity from ejector and switch valve to pad (l)
- Q : Smaller one between the Q1 and Q2 ℓ/min (ANR)
- Q1: Average suction flow (d/min (ANR)) Calculation of average suction flow
  - Ejector  $Q_1 = (1/2 \text{ to } 1/3) \text{ x Ejector}$
  - Max. suction flow e/min (ANR) · Vacuum pump
  - $Q_1 = (1/2 \text{ to } 1/3) \times 11.1$
  - x Effective area of vacuum pump (mm<sup>2</sup>)
- Q2: Max. flow from ejector and switch valve to pad by piping system  $Q_2 = S \times 11.1 \ell/min (ANR)$
- S : Effective area of piping (mm<sup>2</sup>)

#### Selection Graph 1. Tubing piping capacity

Piping capacity from ejector and switch valve at vacuum pump to pad can be found from selection graph (3).

#### Selection Graph (3) Tubing I.D. Piping Capacity



#### How to read the graph

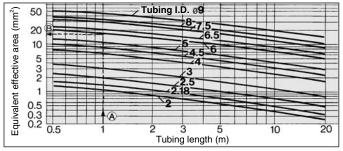
Example: For obtaining the volume of tubing I.D. ø5 mm and 1 meter length.

#### Selection Procedure

By extending leftward from the point at which the 1 meter tubing length on the horizontal axis intersects the line for a tubing I.D. ø5 mm, the piping volume approximately equivalent to 0.02  $\ell$  can be obtained, on the vertical axis. Piping capacity  $\approx 0.02 \ell$ 

#### 2. Effective area of tubing

Effective area of tubing from graph below



#### How to read the graph

Example: Tubing size ø8/ø6, 1 m

#### **Selection Procedure**

From the point of intersection of tubing length 1 m of lateral axis and tubing I.D. ø6 mm, the equivalent effective area at vertical axis can be found as approx. 18 mm<sup>2</sup>.

Equivalent effective area ~ 18 mm<sup>2</sup>



# Selection Step 2 Selection of Ejector and Vacuum Switch Valve

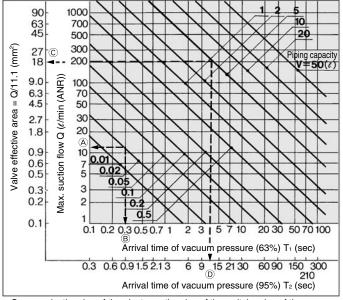
# 2-A Adsorption Response Time

#### Selection Graph

#### 3. Obtaining the adsorption response times

By operating the supply valve (switch valve) that controls the ejector (vacuum pump), the adsorption response times  $T_1$  and  $T_2$  that elapsed before the prescribed vacuum pressure is reached can be obtained using the selection graph (4).

#### Selection Graph (4) (Adsorption Response Time)



\* Conversely, the size of the ejector or the size of the switch valve of the vacuum pump system can be obtained from the adsorption response time.

#### How to read the graph

**Example 1**: For obtaining the adsorption response time until the pressure in the piping system with a piping volume of 0.02  $\ell$  is discharged to 63% (T<sub>1</sub>) of the final vacuum pressure through the use of the vacuum ejector ZH07 $\Box$ S with a maximum suction flow of 12  $\ell$ /min (ANR).

#### **Selection Procedure**

From the point at which the vacuum ejector's maximum suction flow of 12  $\ell$ /min (ANR) and the piping volume of 0.02  $\ell$  intersection, the adsorption response time T<sub>1</sub> that elapses until 63% of the maximum vacuum pressure is reached can be obtained. (Sequence in selection graph (4), A $\rightarrow$ B) T<sub>1</sub>  $\approx$  0.3 seconds.

**Example 2**: For obtaining the discharge response time until the internal pressure in the 5  $\ell$  tank is discharged to 95% (T<sub>2</sub>) of the final vacuum pressure through the use of a valve with an effective area of 18 mm<sup>2</sup>.

#### Selection Procedure

From the point at which the valve's effective area of 18 mm<sup>2</sup> and the piping volume of 5  $\ell$  intersection, the discharge response time (T<sub>2</sub>) that elapses until 95% of the final vacuum pressure is reached can be obtained. (Sequence in selection graph (4), C $\rightarrow$ D) **T**<sub>2</sub>  $\approx$  **12 seconds.** 

## 2-B Leakage during Workpiece Adsorption

#### Leakage

Even if the pad picks up a workpiece, air could be drawn in depending on the type of the workpiece. As a result, the vacuum pressure in the pad becomes reduced and the amount of vacuum that is necessary for adsorption cannot be attained.

When this type of workpiece must be handled, it is necessary to select the proper size of the ejector and the vacuum switch valve by taking into consideration the amount of air that could leak through the workpiece.



#### Leakage from Effective Area of Workpiece

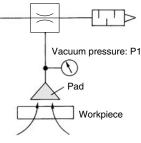
Leakage Q∟ = 11.1 x S∟

- Q∟: Leakage (ℓ/min (ANR))
  - SL: Effective area between a workpiece and a pad, and the workpiece opening area (mm<sup>2</sup>)

#### Leakage from Adsorption Test

As described in the illustration below, pick up a workpiece using an ejector, pad and vacuum gauge.

At this time, read the vacuum pressure P<sub>1</sub>, and obtain the suction flow using flow characteristics graph for the ejector that is being used, and render this amount as the leakage of the workpiece.



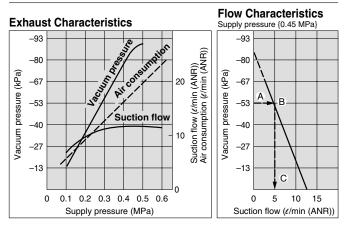
**Exercise**: Using a supply pressure of 0.45 MPa, when the ejector (ZH07) picks up a workpiece that leaks air, the vacuum gauge indicated a pressure of -53 kPa. Calculate the leakage volume from the workpiece.

#### **Selection Procedure**

When the suction flow at –53 kPa is obtained using the ZH07DS flow characteristics graph, the leakage volume is 5 t/min (ANR). (A $\rightarrow$ B  $\rightarrow$ C)

Leakage ≈ Suction flow 5 ℓ/min (ANR)

#### ZH07□S



# Selection Step 2 Selection of Ejector and Vacuum Switch Valve

## 2-C Sizing Ejector and Vacuum Switch Valve (with Leakage)

If there is leakage through a workpiece, the necessary size of the ejector and the vacuum switch valve can be obtained by adding the leakage volume to the maximum suction flow.

#### Calculation

1. Average suction flow to achieve adsorption response time

$$Q = \frac{V \times 60}{T_1} + Q_L$$
$$T_2 = 3 \times T_2$$

Q : Average suction flow *c*/min (ANR)

- V : Piping capacity (*l*)
- T1 : Arrival time to stable Pv 63% after adsorption (sec)
- T2 : Arrival time to stable Pv 95% after adsorption (sec)
- QL: Leakage during workpiece adsorption ℓ/min (ANR)

#### 2. Max. suction flow

Qmax = (2 to 3) x Q  $\ell$ /min (ANR)

#### **Selection Procedure**

#### Ejector

Select the ejector with the greater maximum suction flow from the Qmax. given above.

#### • Direct-operated switch valve

Effective area S = 
$$\frac{Qmax}{11.1}$$
 (mm<sup>2</sup>)

Note) Select a valve (solenoid valve) having an effective area that is greater than that of the effective area formula given above from the related equipment.

# Selection Graph

#### 1. Tubing capacity

Using selection graph (3) (page 3) "Tubing I.D. Piping Capacity", obtain the tubing capacity.

#### 2. Max. suction flow Qmax

Using selection graph (4) (page 4) "Adsorption Response Time", obtain the maximum suction flow Q that does not contain the leakage amount  $Q_{L}$ , based on the set adsorption response times (T<sub>1</sub>, T<sub>2</sub>) and the tubing volume.

#### Max. suction flow $Qmax = Q + (3 \times Q_{L})$

- **Q** : Max. suction flow from selection graph (4) "Adsorption Response Time" on page 4
- QL: Leakage volume *t*/min (ANR) (page 4) (2) B from leakage when adsorbing up a workpiece

#### **Selection Procedure**

#### Ejector

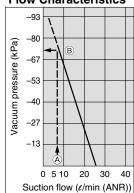
Select an ejector having a greater maximum suction flow than that of Qmax given above. During the selection, verify the pad's lift force because the vacuum pressure after ad-

sorption will be lower than the maximum vacuum pressure due to the leakage volume  $Q_{\perp} t/min$  (ANR).

#### Example: ZH10 S

(Supply pressure 0.45 MPa) If the leakage volume  $Q_{L}$  is 12  $\ell$ /min (ANR), the vacuum pressure after adsorption will be -73 kPa. (A $\rightarrow$ B)

#### Flow Characteristics



• Vacuum switch valve Using selection graph (4) (page 4), move the maximum suction flow Qmax. point parallel to the graduation line of the effective area S of the left valve; then, obtain the effective area of the vacuum switch valve from the intersecting point.

# 2-D Sizing Ejector and Vacuum Switch Valve (without Leakage)

Calculation -

#### 1. Average suction flow

$$Q = \frac{V \times 60}{T_1}$$

$$I_2 = 3 \times I_1$$

Q : Average suction flow ℓ/min (ANR) V : Piping capacity

- $T_1$ : Arrival time to stable Pv 63% after adsorption (sec)
- $T_2$ : Arrival time to stable PV 95% after adsorption (sec)
- 2. Max. suction flow

Qmax = (2 to 3) x Q 
$$\ell$$
/min (ANR)

#### Selection Procedure

#### Ejector

Select the ejector with the greater maximum suction flow from the Qmax. given above.

• Vacuum switch valve  
Effective area S = 
$$\frac{Qmax}{11.1}$$
 (mm<sup>2</sup>)

Note) Select a valve (solenoid valve) having an effective area that is greater than that of the effective area formula given above from the related equipment.

## Selection Graph -

#### 1. Tubing capacity

Using tubing capacity selection graph (3) (page 3) "Tubing I.D. Piping Capacity", obtain the tubing capacity.

#### 2. Max. suction flow Qmax

Using selection graph (4) (page 4) "Adsorption Response Time", obtain the maximum suction flow Q based on the set adsorption response times ( $T_1$ ,  $T_2$ ) and the tubing volume.

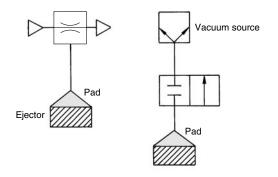
#### **Selection Procedure**

#### • Ejector

Select an ejector having a greater maximum suction flow than that of Qmax. given above.

#### Vacuum switch valve

Using valve selection graph (4) (page 4), move the maximum suction flow Qmax point parallel to the graduation line of the effective area S of the left valve; then, obtain the effective area of the vacuum switch valve from the intersecting point.

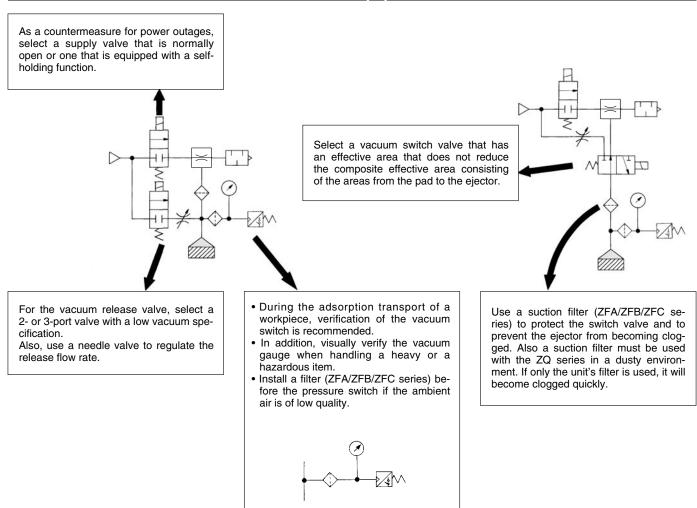




# **Vacuum Equipment Model Selection**

# \land Caution

## **Caution on Vacuum Equipment Selection**



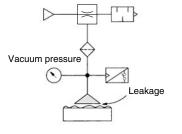
# **A** Caution

#### Caution on Matching with Vacuum Circuit Diagram Ejector and number of pads Vacuum pump and number of pads Vacuum line Vacuum source Tank Ţυ IN Ideally, one pad should be When more than one pad is attached to a Ideally, one pad should be When more than one pad is attached to a single ejector, if one of the workpieces used for each ejector. used for each ejector. single vacuum line, take the countermeasures becomes detached, the vacuum pressure will listed below. drop, causing other workpieces to become • Adjust the needle valve to minimise the detached. Therefore, the countermeasures pressure fluctuation between adsorption and listed below must be taken. non-adsorption operation. • Adjust the needle valve to minimise the · Include a tank and a vacuum pressure pressure fluctuation between adsorption reduction valve (vacuum pressure regulator and non-adsorption operations. valve) to stabilize the source pressure. · Provide a vacuum switch valve to each · Provide a vacuum switch valve to each individual pad to minimise the influences on individual pad to minimise the influences on other pads if an adsorption error occurs. other pads if an adsorption error occurs.



# **Vacuum Equipment Model Selection**

# ▲ Caution Caution on Ejector Nozzle Diameter Selection



If a considerable amount of leakage occurs between the workpiece and the pad, resulting in incomplete adsorption, or to shorten the adsorption transport time, select an ejector nozzle with a larger diameter from the ZH/ZM/ZR/ZL/ZQ series.

# Vacuum Switch (Series ZS), Vacuum Gauge (Series GZ)

When adsorbing and transporting a workpiece, verify at the vacuum switch as much as possible (In addition, visually verify the vacuum gauge, especially when handling a heavy or a hazardous item.). When picking an electronic part or a small precision part, if the suc-

Note the provided of the second state of the

# **Caution on Pad Selection**

Set the operating pressure below the pressure that has been stabilized after adsorption and determine the pad diameter in accordance with the operating pressure.

During the selection of a pad, keep in mind that the vacuum pressure during the adsorption of a workpiece that leaks becomes lower than the maximum vacuum pressure.

# **Caution on Vacuum Line Equipment Selection**

Determine the volume of the suction filter and the effective area of the switching valve in accordance with the maximum suction flow of the ejector and the vacuum pump. Make sure that the effective area is greater than the value that has been obtained through the formula given below. (If the devices are connected in series in the vacuum line, their effective areas must be combined.)

> S = Qmax/11.1 S: Effective area (mm<sup>2</sup>) Qmax: Max. suction flow *c*/min (ANR)

# Suction Filter (Series ZFA/ZFB/ZFC)

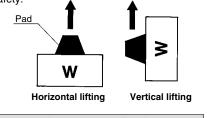
- To protect the switching valve and the ejector from becoming clogged, a suction filter in the vacuum circuit is recommended.
- When using the ZQ series in a dusty environment, the unit's filter will become clogged quickly, so it is recommended to use the ZFA/ZFB/ZFC series concurrently.

# Safety

Because suction is applied to an object during a vacuum adsorption transport, there is a possibility of dropping the object depending on the conditions. Thus, everything should be designed with safety as the number one priority in order to achieve a system design with an excellent margin of safety.

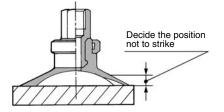
# **Mounting Position**

As a rule, the unit must be installed horizontally. Although a diagonal or a vertical installation should be avoided whenever possible, if the unit must be installed in such a manner, be certain to guarantee absolute safety.



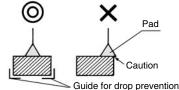
# Impact to Pad

When pushing a pad to a workpiece, make sure not to apply an impact or a large force which would lead to premature deformation, cracking, or wearing of the pad. Therefore, the pad should be pushed against the workpiece to the extent that its skirt portion deforms or that its ribbed portion comes into slight contact with the workpiece. Especially, when using a smaller diameter pad, make sure to locate it correctly.

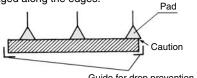


## Balance of Pad and Workpiece

Make sure that the pad's suction surface is not larger than the surface of the workpiece to prevent vacuum leakage and unstable picking.



If multiple pads are used for transporting a flat object with a large surface area, properly allocate the pads to maintain balance. Also make sure that the pads are aligned properly to prevent them from becoming disengaged along the edges.



Guide for drop prevention

Provide an auxiliary device (example: a guide for preventing the workpieces from dropping) as necessary.

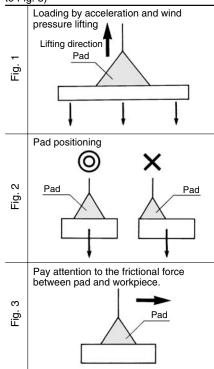
# Vacuum Pad Applications

## Lifting Force, Moment, Horizontal Force

To lift a workpiece vertically, make sure to take into consideration the acceleration rate, wind pressure, impact, etc., in addition to the weight of the workpiece. (Refer to Fig. 1) Because the pads are susceptible to mo-

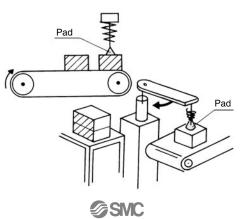
ments, mount the pad so as not to allow the workpiece to create a moment. (Refer to Fig. 2)

2) When a workpiece that is suspended horizontally is moved laterally, the workpiece could shift depending on the extent of the acceleration rate or the size of the friction coefficient between the pad and the workpiece. Therefore, the acceleration rate of the lateral movement must be minimised. (Refer to Fig. 3)



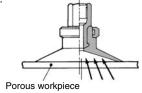
# Unsteady Distance between Pad and Workpiece

If the pad and the workpiece cannot be positioned properly, such as when picking a workpiece having an uneven height, use a built-in spring type pad with a buffer. This type of pad acts as a cushion between the pad and the workpiece. If it is necessary to further position the pad and the workpiece, use a non-rotating buffer.



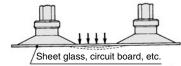
## **Porous Workpiece**

To pick a permeable workpiece such as paper, select a pad with a small diameter that is sufficient to lift the workpiece. Because a large amount of air leakage could reduce the pad's suction force, it may be necessary to increase the capacity of the vacuum pump or enlarge the effective area of the piping passage.



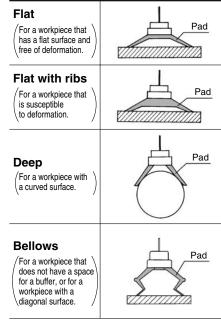
### Flat Plate Workpiece

When a workpiece with a large surface area such as sheet glass or PCB is suspended, the workpiece could move in a wavelike motion if a large force is applied by wind pressure or by an impact. Therefore, it is necessary to ensure the proper allocation and size of pads.



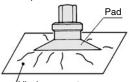
# Pad Form Selection by Workpiece

To use an appropriate pad, select the shape of the pad in accordance with the shape and the material of the workpiece.



# Soft Workpiece

If a soft workpiece such as vinyl, paper, or thin sheet is picked up, the vacuum pressure could cause the workpiece to deform or wrinkle. In such a case, it will be necessary to use a small pad or a ribbed pad and reduce the vacuum pressure.



Vinyl, paper, etc.

# Vacuum Equipment Model Selection

# Vacuum Pad: Workpiece Transfer Examples

# Materials

Material	Applications
NBR	Transport of general workpiece, Cardboard, Veneer plate, Iron plate and others
Silicon rubber	Semiconductor, Removing from die-casting, Thin workpiece
Urethane rubber	Cardboard, Iron plate, Veneer plate
Fluoro rubber	Chemical workpiece
Conductive NBR	General workpiece of semiconductor (Static electricity resistance)
Conductive silicon rubber	Semiconductor (Static electricity resistance)

# Pads

Pad form	Applications
Flat	For when adsorption surface of a workpiece is flat and not deformed.
Flat with ribs	For when a workpiece is likely to deform or in the case of releasing a workpiece certainly.
Deep	For when a workpiece is spherical shape.
Bellows	For when there is not enough space to install a buffer or adsorption surface of a workpiece is slanted.
Elliptic	For when a workpiece has limited adsorption surface or length is long and a workpiece is required to locate precisely.
Ball joint type	For when adsorption surface of a workpiece is not horizontal.
Long stroke buffer	For when a workpiece height is not even or cushioning toward a workpiece is required.
Large size buffer	For when a workpiece is heavy weight.
Conductive pad	As one of the countermeasures against static electricity, rubber material with reduced resistance is used. For antistatic measures

# Glossary

Glossary	
Terms	Description
(Max.) suction flow	Volume of air taken in by the ejector. The maximum volume is the flow rate of the air that is taken in without having anything connected to the vacuum port.
Maximum vacuum pressure	The maximum value of the vacuum pressure that is generated by the ejector.
Air consumption	The volume of compressed air that is consumed by the ejector.
Standard supply pressure	The optimal supply pressure for operating the ejector.
Exhaust characteristics	The relationship between the vacuum pressure and the suction flow when the supply pressure to the ejector has been changed.
Flow characteristics	The relationship between the vacuum pressure and the suction flow with the standard supply pressure supplied to the ejector.
Vacuum pressure switch	The pressure switch that is used for verifying the adsorption of a workpiece.
Adsorption verification switch	The switch, based on an air pressure bridge, that is used for verifying the adsorption of a workpiece. It is used when the adsorption pad and the nozzle are extremely small.
(Air) supply valve	The valve that supplies compressed air to the ejector.
(Vacuum) release valve	The valve that supplies positive pressure or air to break the vacuum state of the adsorption pad.
Flow adjustment valve	The valve that supplies positive pressure or air that regulates the flow of the air to break the vacuum.
Release pressure	Pressure that is used for breaking the vacuum.
Pilot pressure	Pressure that is used for operating the ejector valve.
External release	The action of breaking the vacuum using externally supplied air instead of using the ejector unit.
Vacuum port	Port for generating vacuum.
Exhaust port	Port for exhausting the air, which was used by the ejector, and the air taken in by vacuum port.
Supply port	Port for supplying the air, which is used by the ejector.
Back pressure	Pressure inside the exhaust port.
Leakage	The entry of air into the vacuum passage, such as from an area between a workpiece and a pad, or between a joint and tubing. The vacuum pressure decreases when leakage occurs.
Response speed	The time that elapses from when the supply valve or the switching valve is activated until the pressure switch turns ON. It is also called the adsorption response time.
Average suction flow	The suction flow of the ejector or the pump, which is used for calculating the response speed. It is 1/2 to 1/3 of the maximum suction flow.
Conductive pad	A pad with a low electrical resistance that is used as an electrostatic prevention measure.
Vacuum pressure	Any pressure below the atmospheric pressure. When the atmospheric pressure is used as a reference, the pressure is presented by -kPa (G), and when the absolute pressure is used as a reference, the pressure is represented by kPa {abs}. When referencing a piece of vacuum equipment such as an ejector, the pressure is generally represented by -kPa.
(Vacuum) ejector	A device that generates vacuum by means of discharging the compressed air from a nozzle at a high speed, thus utilizing the phenomenon in which the pressure is reduced when the air around the nozzle is sucked.
Suction filter	The vacuum filter that is provided in the vacuum passage in order to prevent the intrusion of dust into the ejector, the vacuum pump, or peripheral equipment.

#### **Effective Diameter of Vacuum Pad**

Effective diameter at adsorption is as follows.

#### Vacuum Area Diameter (Vacuum pressure: -84 kPa) after Vacuum Adsorption by Vacuum Pad (mm) Flat with ribs C Flat U Bellows B Deep D Heavy-duty H Heavy-duty bellows HB Type Material Part no. Silicon Silicon Silicon Silicon Silicon Silicon NBR NBR NBR NBR NBR NBR rubber rubber rubber rubber rubber rubber ninal size ZP2004 2004 2 x 4 2 x 4 ZP3507 3.5 x 7 3.5 x 7 3507 ZP4010 4010 4 x 10 4 x 10 ZP02□□ 2 ø2 ø2 ZP04□□ 4 ø4 ø4 ZP06□□ 6 ø5 ø4 ø5 ø5 ZP08□□ 8 ø7 ø7 ø7 ø5 ZP10 10 ø10 ø9 ø10 ø9 ø8 ø7 ø10 ø10 \_\_\_\_ \_ \_ \_\_\_\_ ZP13□□ 13 ø11 ø11 ø11 ø11 ø8 ø9 ZP16 16 ø10 ø12 ø9 ø13 ø13 ø10 ø9 ø14 ZP20□□ 20 ø14 ø14 ø13 ø13 ø12 ø15 ZP25 25 ø14 ø13 ø18 ø17 ø15 ø15 ø19 ø16 ZP32 32 ø13 ø11 ø21 ø20 ø20 ø19 ø32 ø27 ø26 ø26 ZP40□□ 40 ø20 ø17 ø24 ø25 ø24 ø24 ø33 ø29 ø39 ZP50□□ 50 ø18 ø17 ø33 ø30 ø35 ø33 ø42 ø42 ø36 ZP63□□ 63 ø49 ø49 ø46 ø45 80 ø60 ø60 ø57 ø56 ZP80 100 ø78 ø78 ø69 ø71 ZP100 125 ø102 ø101 ø92 ø91 ZP125

# Proposals for Using the Vacuum Equipment

Please consider the following items in order to enable the vacuum ejector and the vacuum pump system to operate more effectively. Graph 1 shows the timing of a typical operational pattern.

The responsiveness can be increased depending on the condition.

#### 1. Timing for generating vacuum

The timing for opening/closing the valve will be counted if a vacuum is generated after the adsorption pad descends to absorb a workpiece. Also, there is a timing delay risk for the generating vacuum since the operational pattern for the verification switch, which is used for detecting the descending adsorption pad, is not even.

To solve this issue, we recommend that vacuum be generated in advance, before the adsorption pad begins to descend to the workpiece.

Adopt this method after confirming that there will be no misalignment resulting from the workpiece's light weight.

#### 2. Adsorption verification

In the case of lifting the adsorption pad after absorbing a workpiece, confirm that there is a suction verification signal from the vacuum switch, before the adsorption pad is lifted. If the adsorption pad is lifted, based on the timing of a timer, etc., there is a risk that the workpiece may be left behind.

In general pick and place applications, the time for absorbing a workpiece is slightly different since the position of the adsorption pad and the workpiece are different after every operation. Therefore, program a sequence in which the suction completion is verified by a vacuum switch, etc. before moving to the next operation.

#### 3. Supply pressure

3.1 Use the vacuum ejector with the standard supply pressure.

When the product is supplied with the standard pressure, the maximum vacuum pressure and the maximum suction flow are performed, resulting in the improved response time for adsorption.

Using a standard supply pressure is also the most effective way to save energy If an excessive supply pressure is used, the ejector peformance is reduced. Do not use the product with more than the standard supply pressure.

3.2 Excessive supply line pressure may occur when the operation is suspended (holidays, night time, etc.). Please use a separate regulator to gain sufficient flow in the upstream side of the ejector supply pressure pipings.

#### 4. Set pressure for the vacuum pressure switch

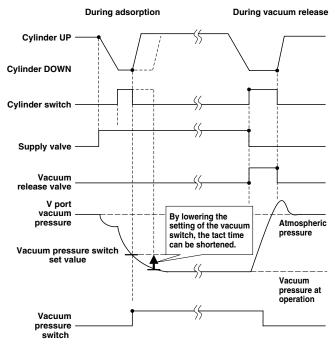
Set the optimum value after calculating the required vacuum pressure for lifting a workpiece.

If a higher pressure than required is set, there is a possibility of being unable to confirm the suction even though the workpiece is absorbed. This will result in a suction error.

When the tact time is emphasised, you should set using a lower pressure, with which a workpiece can be adsorped, only after considering the acceleration or vibration when a workpiece is transfered.

#### 5. Equipment with vacuum equipment

Carefully perform a debugging operation beforehand in equipment having vacuum products such as a handler, chip mounter, etc. Before actually using the equipment, carefully confirm the operation and perform a trial run, etc.



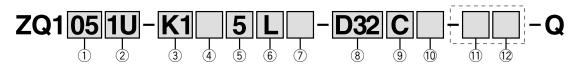
Graph 1. Example of a typical operational pattern timing



# Space Saving Vacuum Ejector

# How to Order

# **Ejector Unit**



#### 1 Nozzle nominal size

(2) Exhaust type
------------------

05	ø0.5
07	ø0.7
10	ø1.0

	1U	With silencer for single unit
	3М	With silencer for manifold

# **3** Solenoid valve combination

Symbol	Supply valve	Vacuum release valve
K1	Normally closed	Normally closed
K2 Note 1)	Normally open	Normally closed
J1	Normally closed	None
J2 Note 1)	Normally open	None
Q1	Latching positive common	Normally closed
Q2	Latching positive common	None
N1	Latching negative common	Normally closed
N2	Latching negative common	None

Note 1) In cases when K2 or J2 (supply valve normally open) is selected for the solenoid valve combination, when vacuum is stopped for long periods of time (10 minutes or more), do not continue to energize the supply valve, and shut off the air supply.

## ④ Pilot valve

—	Standard (DC: 1 W) Note 2)
Y	DC low wattage type (0.5 W) Note 3)

Note 2) Avoid energizing the solenoid valve for long periods of time. (Refer to Design and Selection on Specific Product

Precautions 1.) Note 3) Y option only available for solenoid valve combinations K1 and J1.

# **(5)** Solenoid valve rated voltage

5	24 VDC
6	12 VDC

# 6 Electrical entry

L	L-type plug connector, with 0.3 m lead wire, with light/surge voltage suppressor	
LO	L-type plug connector, without connector, with light/surge voltage suppressor	
G	Grommet, with 0.3 m lead wire (Latching/AC type: Not applicable)	

#### 7 Manual override Note 4)

_	Non-locking push type Latching type: Push-locking type				
В	Locking type (Q1/Q2/N1/N2: Not applicable)				
Note 4) Latching type supply valve: Available in "-" only. In					
this case, the supply valve and vacuum release valve					
come with a lock.					

#### 8 Vacuum pressure switch suction filter Note 5)

F	With suction filter only	
D32	2 NPN outputs, with suction filter, Pressure range –100 to 0 kPa	
D52	2 PNP outputs, with suction filter, Pressure range –100 to 0 kPa	
Pressure range – 100 to 0 kPa		

Note 5) The filter included in this product is of an simple type, and will become clogged quickly in environments with high quantities of dust or particulates. Please make additional use of an air suction filter of the ZFA, ZFB or ZFC series.

#### (9) Vacuum switch electrical entry

С	Connector type, with 0.6 m lead wire
CL	Connector type, with 3 m lead wire

# **∆**Warning

The filter case of this suction filter is made of nylon. Contact with alcohol or similar chemicals may cause it to be damaged. Also, do not use the filter when these chemicals are present in the atmosphere.

#### 10 Check valve Note 6)

_	None	
К	With check valve	

Note 6) The check valve has a function to prevent the exhaust air from the silencer overflowing to the vacuum port side when a manifold is used. However, depending on usage conditions, it does not always suppress air overflow to the desired extent. During usage, please inspect thoroughly with actual machine. Also, in order to completely prevent the overflow of exhaust air, leave plenty of space between the check valve unit and adjacent ejector to avoid interference from the ejector's exhaust unit.

## **∆**Warning

Cannot be used for vacuum retention.
 Use a release valve. (Without a release valve, a workpiece may not be released.)

#### 1 Fitting (V port) Note 7)

Symbol	Applicable tubing O.D.	Part no.
0	Without fitting (M5 x 0.8)	_
1	ø3.2 (Straight)	KJS23-M5
2	ø4 (Straight)	KJS04-M5
3	ø6 (Straight)	KJS06-M5
4	ø3.2 (Elbow)	KJL23-M5
5	ø4 (Elbow)	KJL04-M5

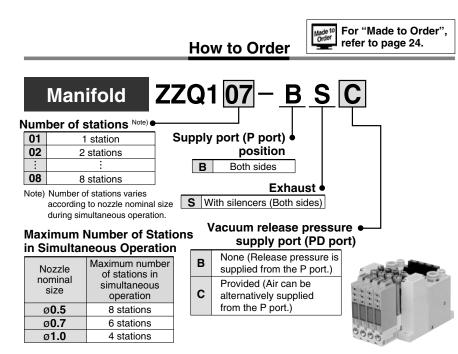
Note 7) When neither V port fitting nor P port fitting are needed, enter nothing or –00 in the dotted line above "How to Order".

#### 12 Fitting (P port) Note 7,8)

Symbol Applicable tubing O.D.		Part no.
0	Without fitting (M5 x 0.8)	—
2	ø4 (Straight)	KJS04-M5
3	ø6 (Straight)	KJS06-M5
5	ø4 (Elbow)	KJL04-M5

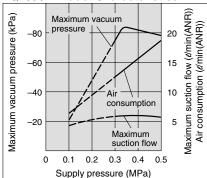
Note 8) Manifold type: Not applicable

# Series **ZQ**

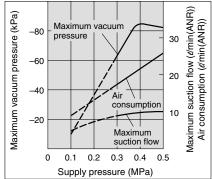


# Flow/Exhaust Characteristics

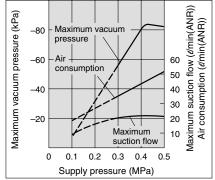
# ZQ105 / Exhaust Characteristics

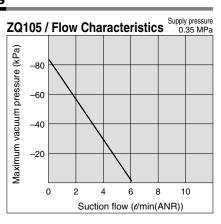


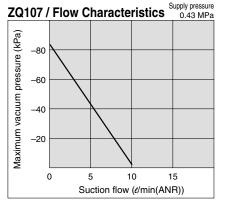
## ZQ107 / Exhaust Characteristics

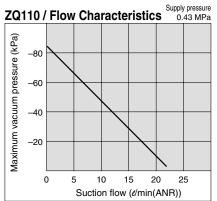


## ZQ110 / Exhaust Characteristics



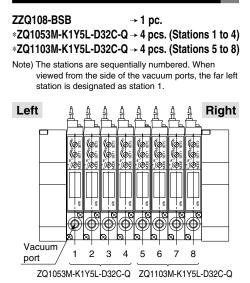




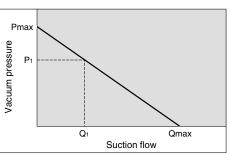


@SMC

# Manifold Ordering Example



# How to Read Flow Characteristics



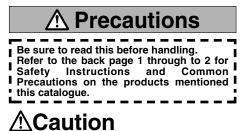
Flow characteristics are expressed in ejector vacuum pressure and suction flow. If suction flow rate changes, a change in vacuum pressure will also be expressed. Normally this relationship is expressed in ejector standard use.

In the graph, Pmax. is max. vacuum pressure and Qmax is max. suction flow. The valves are specified according to catalogue use. Changes in vacuum pressure are expressed in the below order.

- 1. When ejector suction port is covered and made airtight, suction flow becomes 0 and vacuum pressure is at maximum value (Pmax).
- When suction port is opened gradually, air can flow through, (air leakage), suction flow increases, but vacuum pressure decreases. (condition P1 and Q1)
- When suction port is opened further, suction flow moves to maximum value (Qmax), but vacuum pressure is near 0. (atmospheric pressure).

When vacuum port (vacuum piping) has no leakage, vacuum pressure becomes maximum, and vacuum pressure decreases as leakage increases. When leakage value is the same as max. suction flow, vacuum pressure is near 0.

When leaky work must be adsorbed, please note that vacuum pressure will not be high.



Refer to page 1 through to 10 for the product selection in the ZQ series and the sizing program.

# Specifications

## Ejector

Model	ZQ105	ZQ107	ZQ110	
Nozzle nominal diameter (mm)	0.5	0.7	1.0	
Maximum suction flow (//min (ANR))	5	10	22	
Air consumption (dmin (ANR))	14 23 46		46	
Maximum vacuum pressure	-80 kPa			
Supply pressure range	0.3 to 0.5 MPa (Normally open: 0.3 to 0.45 MPa)		MPa)	
Supply pressure Note)	0.35 MPa 0.45 MPa		MPa	
Operating temperature range	5 to 50°C			

Note) Maximum suction flow can be obtained by standard supply pressure.

## Weight

Single	With suction filter Note 1)	95 g
unit	With switch and suction filter Note 2)	109 g
End plate assembly for manifold		122 g

Note 1) Including a 0.3 m connector for supply valve and vacuum release valve.

Note 2) Including a 0.3 m connector for supply valve and vacuum release valve and a 0.6 m connector for switch.

#### $\ensuremath{\bigcirc}$ Calculation of weight for the manifold type

(Single unit weight) x (Number of stations) + (Weight of end plate assembly for manifold)

Example) Switch + 8 stations with suction filter

109 g x 8 + 122 g = 994 g

# Supply Valve / Vacuum Release Valve

Туре		Normally closed			Newselleseses
		Standard (1 W)	Low wattage type (0.5 W)	Latching type	Normally open
Model ( Refer to "How to Order" for ( solenoid valves on page 16.)		VQ110-□	VQ110Y-□	VQ110 <mark>⊾</mark> -□	ZQ1-VQ120-□
Fluid			Air / In	ert gas	
Maximum operating p	ressure		0.5 MPa		0.45 MPa
Minimum operating pressure		0.3 MPa			
Ambient and fluid temperature		5 to 50°C			
Lubrication		Not required			
Manual override		Non-locking push type / Locking type (Tool type) Push		Push-locking type	Non-locking push type / Locking type (Tool type)
Rated coil voltage		12, 24 VDC	12, 24 VDC	12, 24 VDC	12, 24 VDC
Power consumption (current value)         DC         1 W         0.5 W		W			
Electrical entry		Gror	nmet	L-type plug connector Gromm	
		L-type plug (with light/surge ve	connector oltage suppressor)	(with light/surge voltage suppressor) L-type plug conn (with light/surge voltage suppressor)	



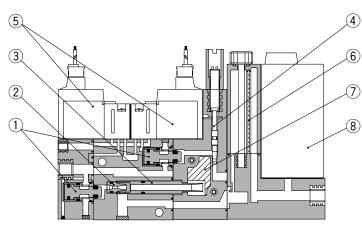
# Specifications

# Vacuum Pressure Switch

	Model to "How to Order" for vacuum ssure switches on page 16.	ZQ1S-D32□-□-AS	ZQ1S-D52□-□-AS	
Rated	pressure range	0 to -1	00 kPa	
Set pre	essure range	0 to –9	99 kPa	
Withst	and pressure	0.2 MPa		
Fluid		Air / Non-corrosive/N	Non-combustible gas	
Power	supply voltage	12 to 24 V	/DC ±10%	
Curren	t consumption	35 mA or less [with power supply voltage of	24 VDC and switch output ON (with no load)]	
Ambient temperature range		5 to 50°C (with no free	ezing or condensation)	
Ambient humidity range		35 to 85 %RH in operation and saving (with no condensation)		
Withstand voltage		500 VAC for 1 min.		
Insulation resistance		50 M $\Omega$ or more (between live parts and pressure port at 500 VDC Mega)		
Switch output		2 NPN outputs 2 PNP outputs		
	Maximum load current	80 mA (per output)		
	Maximum applied voltage	30 V (for NPN output)		
	Residual voltage	NPN output: 0.8 V or less (at 80 mA inrush), PNP output: 1.2 V or less (at 80 mA discharge)		
	Response time	2 ms o	or less	
Hyster	esis	0 to 15% F.S. or less (variable)	2% F.S. or less (fixed)	
Display	V	2-digit Red LED		
Displa	y accuracy	±3 %F.S. ±2 digits		
Output indicator light		Illuminates when the output is turned ON. (Red LED for OUT1 and Green LED for OUT2)		
Analog	output	(Only applicable to D31 and D51)		
	Output voltage	1 to 5 V ±2.5% F.S. or less		
	Linearity	±0.5 F.S. or less		

# Construction

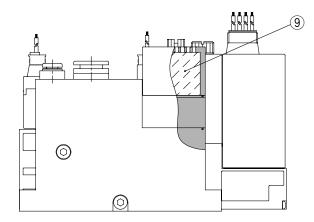
# Single unit



# **Component Parts**

No.	Description	Material
1	Poppet valve assembly	—
2	Nozzle	Aluminum alloy
3	Diffuser	Aluminum alloy
4	Vacuum release flow adjustment needle	Aluminum alloy

# Manifold

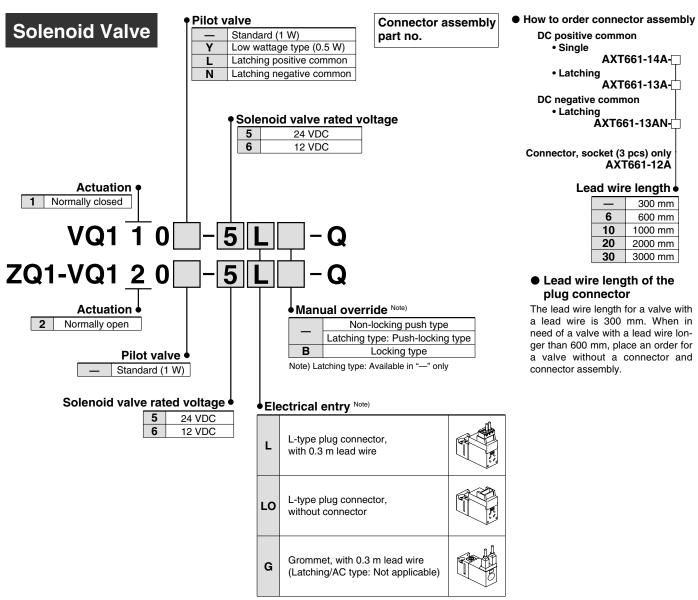


# **Replacement Parts**

No.	Description	Material	Part no.
5	Solenoid valve	—	Refer to page 16.
6	Filter element	PVF	XT534-5-001-AS
7	Sound absorbing material 1 (single unit)	PVF	ZQ-SAE
8	Vacuum pressure switch	—	Refer to page 17.
9	Sound absorbing material 2 (manifold)	PVF	ZZQ-SAE

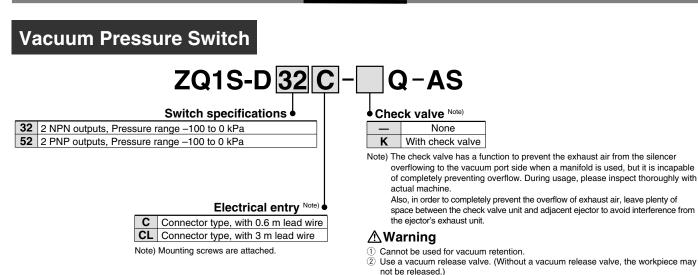
# Space Saving Vacuum Ejector Series ZQ

How to Order



Note) Mounting screws are attached.

# How to Order



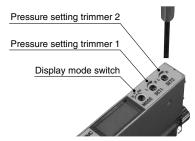
# How to Set Vacuum Pressure Switch

#### How to set pressure

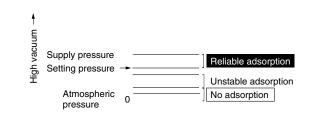
- Pressure trimmer selects the ON pressure. Clockwise rotation increases high vacuum set point.
- When setting, use a flat head screw driver which fits the slot in the trimmer, and turn it gently with your finger tips. (rotational torque: 0.025 N·m or less)

#### When using ZQ1S-D32/-D52-AS

- (a) Set display mode switch (MODE) to "S1".
- (b) Set the Switch 1 operating pressure by rotating the pressure setting trimmer 1 (SET1). (The S1 set operating pressure value will be shown on the display.)
  (c) Set display mode switch (MODE) to "S2".
- (d) Set the Switch 2 operating pressure by rotating the pressure setting trimmer 2 (SET2). (The S2 set operating pressure value will be shown on the display.)
- (e) Return the display mode switch (MODE) to "RUN." (The pressure value of the vacuum port will be shown on the display.)



• When using the switch to confirm correct adsorption, the set pressure should be as low as possible, but not so low that a false confirmation signal is given when adsorption is incomplete.

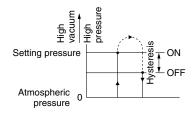


#### Hysteresis

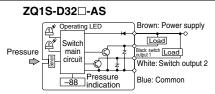
Switch connector part no.

ZQ1-AS-003 ZQ1-AS-004

Hysteresis is the actual pressure variance from set pressure occuring when the output signal turns from ON to OFF. The set pressure is the pressure selected to switch from OFF to ON mode.



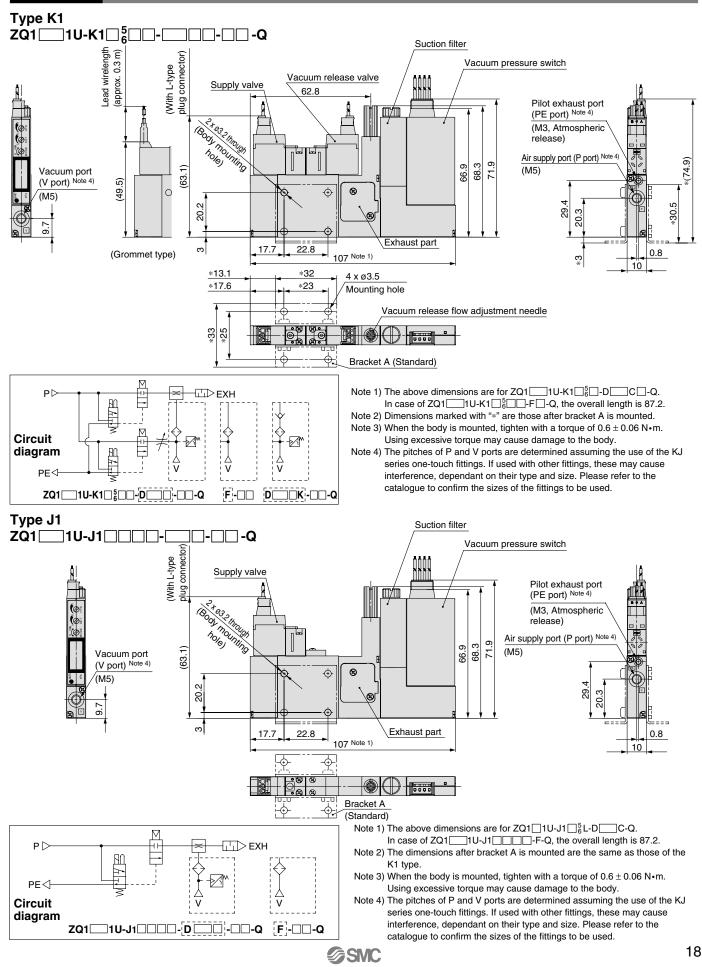
#### Internal Circuits and Wiring Examples



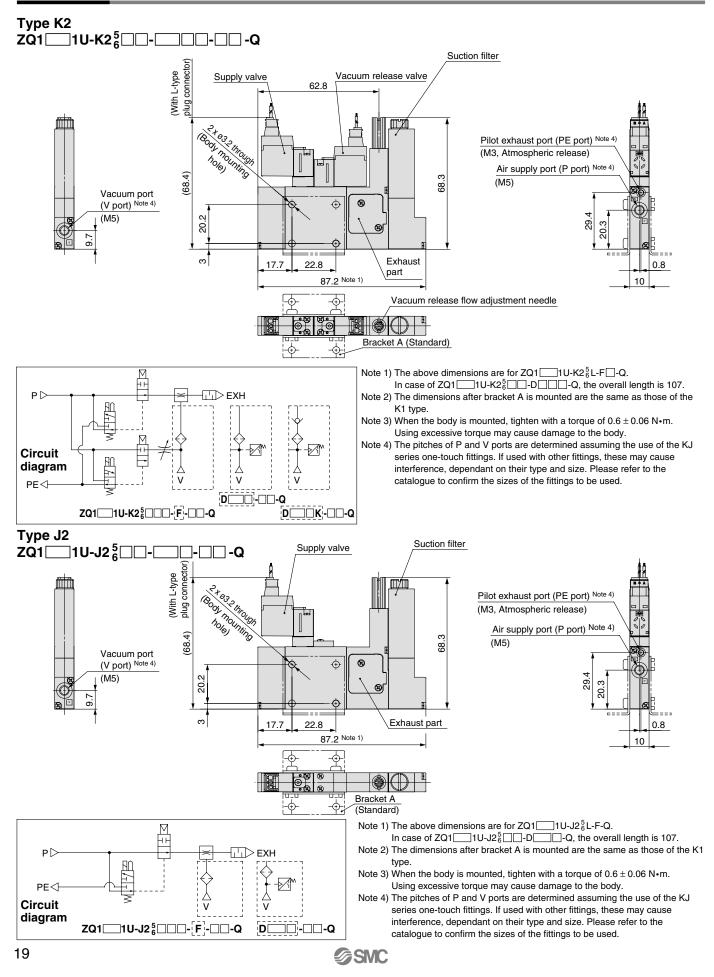
#### ZQ1S-D52D-AS

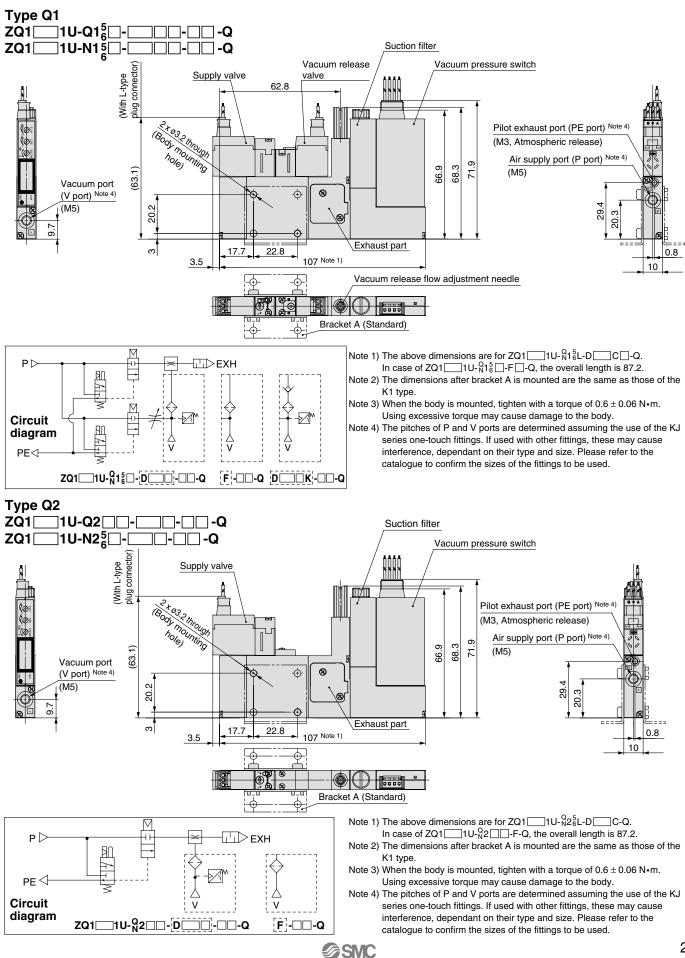
Pressure ⊯⇒	Switch Switch Circuit Switch Switch Pressure -88 indication	Brown: Power supply Black: Switch output 1 White: Switch Load Load Blue: Common
----------------	---	---





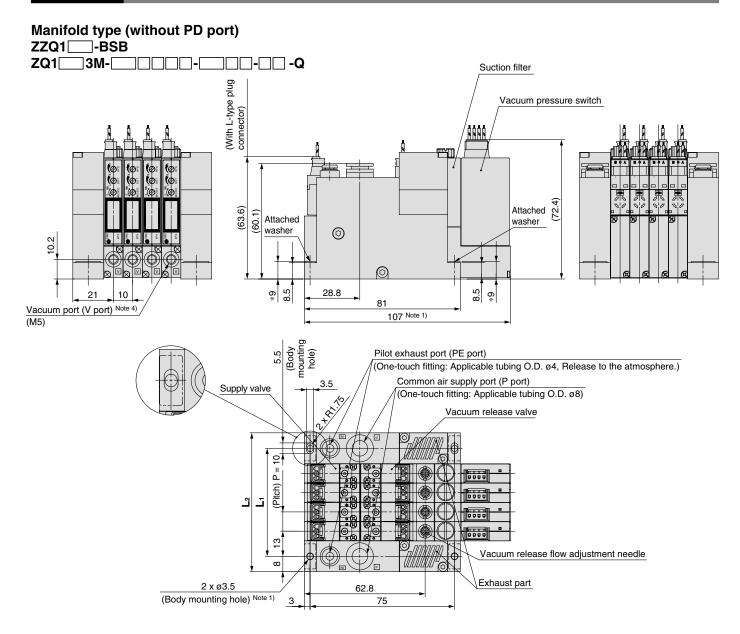
# Series **ZQ**





# Series ZQ

# Dimensions



## Dimensions

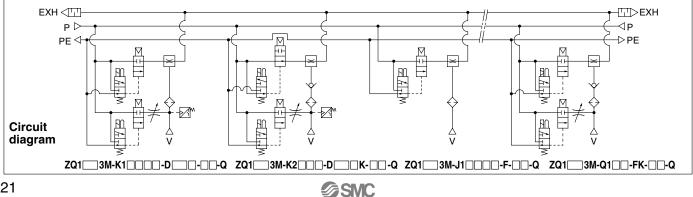
Dimensions								(mm)
n	1	2	3	4	5	6	7	8
L1	26	36	46	56	66	76	86	96
L2	42	52	62	72	82	92	102	112

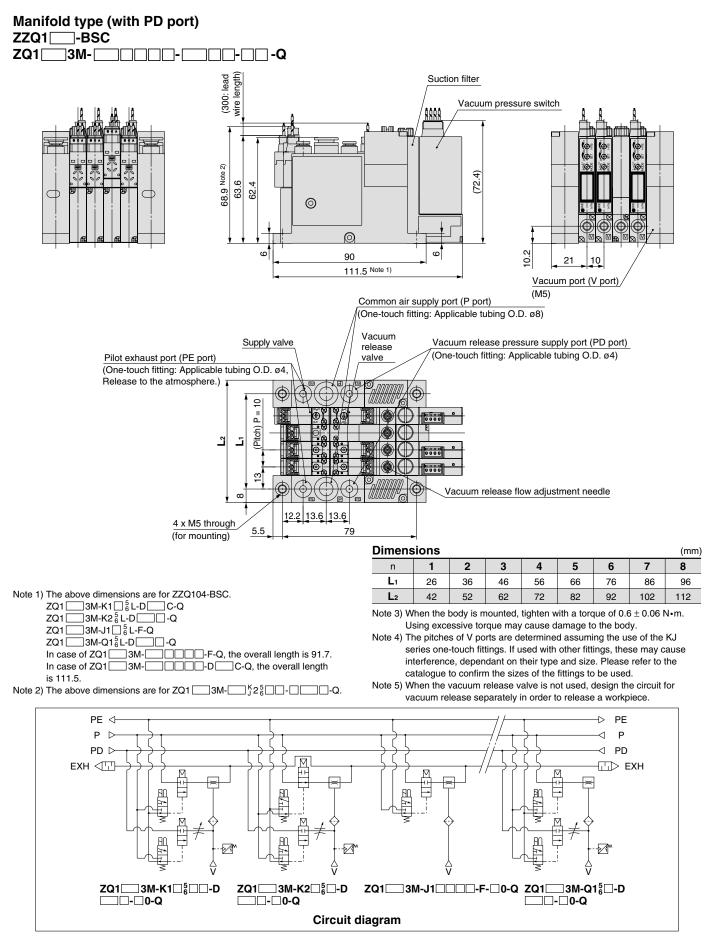
Note 1) The above dimensions are for ZZQ1 -BSB. ZQ1 3M-K1<sup>5</sup><sub>6</sub>L-D C -Q.

Note 3) When the body is mounted, tighten with a torque of 0.6  $\pm$  0.06 N  $\cdot$  m.

Using excessive torque may cause damage to the body. Note 4) The pitches of V ports are determined assuming the use of the KJ series one-

touch fittings. If used with other fittings, these may cause interference, dependant on their type and size. Please refer to the catalogue to confirm the sizes of the fittings to be used.





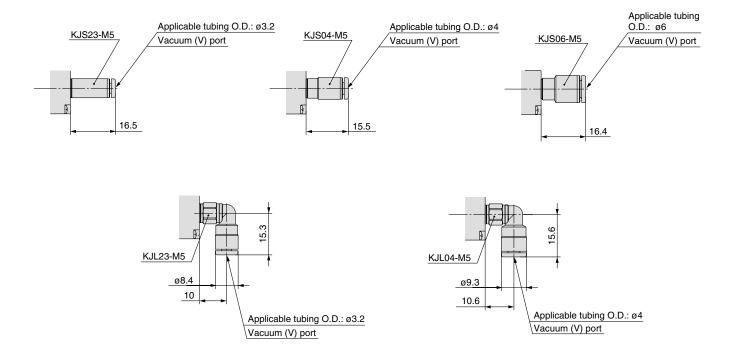




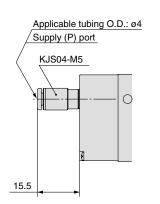
# Fittings / Fitting type filter dimensions after installation

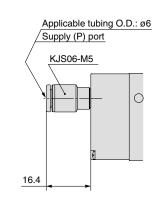
# V port

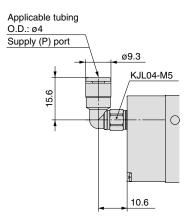
(Suction filter, Vacuum pressure switch)



P port



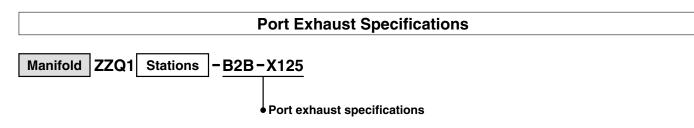




# Space Saving Vacuum Ejector *Series ZQ* Made to Order



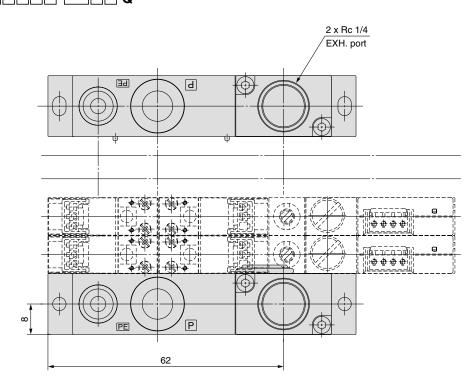
Please contact SMC for detailed dimensions, specifications, and lead times.



Exhaust port is changed for "Port Exhaust Specifications."

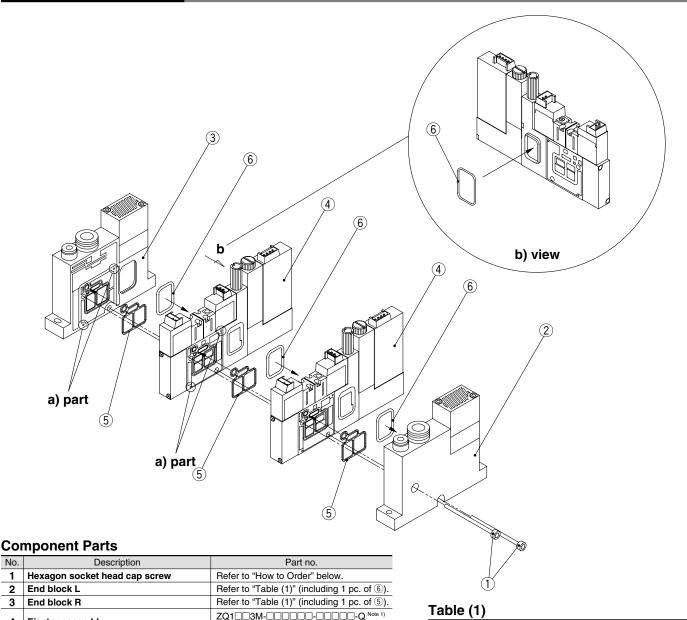
# Dimensions

Manifold type (without PD port) ZZQ1\_\_\_\_-B2B-X125 ZQ1\_\_\_\_3M-\_\_\_\_Q\_-\_\_\_-Q



# Series ZQ

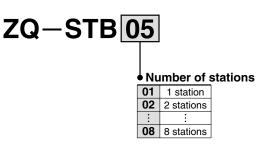
# Manifold Exploded View



4 Ejector assembly (1 pc. each in 5 and 6 is included.) ZQ-3-005-10AS Note 2) 5 Ejector body gasket for manifold ZQ-3-009-10AS Note 2) 6 Exhaust block gasket

Note 1) Refer to pages 11 and 12 for detailed description of "How to Order". Note 2) 10 pcs. are included in one set.

# How to Order Hexagon Socket Head Cap Screw



Note) 2 pcs. are included in one set.

# **Working Procedure**

# Disassembly

Loosen and remove the hexagon socket head cap bolts ①.

Description

End block L

End block R

#### Assembly

1. Install the ejector body gasket for manifold 5 into the gasket groove of each ejector assembly ④. Install the exhaust block gasket (6) around the projected part.

With PD port

ZQ1L-2-BSB-AS

ZQ1R-2-BSB-AS

Without PD port

ZQ1L-1-BSB-AS

ZQ1R-1-BSB-AS

- 2. Install the exhaust block gasket 6 around the projected part of the end block L 2.
- 3. Install the ejector body gasket for manifold 5 into the gasket groove of the end block R 3.
- 4. Align the ejector assemblies ④, end block (L) ②, and end block (R) ③ using positioning pins (at the two "a" positions) and fasten with hexagon socket head cap bolts (1) (2 pcs.) (with a tightening torque of 0.6 N•m  $\pm$  0.06 N•m).

No.

1

2

3



# Space Saving Vacuum Pump System Series ZQ

How to Order

# Vacuum Pump Unit

 $ZQ1000 \bigcup_{1} - \underbrace{K1}_{2} \underbrace{5}_{3} \underbrace{L}_{4} \underbrace{-}_{5} \underbrace{D32}_{6} \underbrace{-}_{7} \underbrace{-}_{8} \underbrace{-}_{9} \underbrace{-}_{10} \underbrace{-}_{10} \underbrace{-}_{9} \underbrace{-}_{10} \underbrace{-}_{9} \underbrace{-}_{10} \underbrace{-}_{$ 

### 1 Body type

U	For single unit	
Μ	For manifold	

#### **2** Solenoid valve combination

Symbol Supply valve		Vacuum release valve		
K1	Normally closed	Normally closed		
K2 Note 1) Normally open		Normally closed		
J1 Normally closed		None		
J2 Note 1) Normally open		None		
Q1 Latching positive common		Normally closed		
Q2	Latching positive common	None		
N1	Latching negative common	Normally closed		
N2 Latching negative common		None		

The air in the adsorption section of this product is not released to the atmosphere at the vacuum suspension state. As for K1, K2, Q1 and N1, use the vacuum release valve when a

workpiece is detached. Concerning J1, J2, Q2 and N2, devise the circuit for the vacuum

release additionally when a workpiece is detached.

Note 1) In cases when K2 or J2 (supply valve normally open) is selected for the solenoid valve combination, when vacuum is stopped for long periods of time (10 minutes or more), do not continue to energize the supply valve, and shut off the air supply.

#### **3** Pilot valve

_	Standard (DC: 1 W) Note 2)	

- Y DC low wattage type (0.5 W) Note 1,3)
- Note 2) Avoid energizing the solenoid valve for long periods of time. (Refer to Specific Product Precautions 1; Caution on
- Design and Selection.) Note 3) Y option only available for solenoid
- valve combinations K1 and J1

## **(4)** Solenoid valve rated voltage

5 24 VDC	
6 12 VDC	

R MAR

## **5** Electrical entry

L	L-type connector, with 0.3 m lead wire, with light/surge voltage suppressor	
LO	L-type connector, without connector, with light/surge voltage suppressor	
G	Grommet, with 0.3 m lead wire (Latching/AC type: Not applicable)	

#### 6 Manual override Note 4)

Non-locking push type     Latching type: Push-locking type			
B Locking type (Q1/Q2/N1/N2: Not applicabl			
Note 4) Latching type supply valve: Available in "Nii" only. this case, the supply valve and release valve com with a lock.			

## Vacuum pressure switch suction filter Note 5)

F	With suction filter only
D32	2 NPN outputs, with suction filter, Pressure range –100 to 0 kPa
D52	2 PNP outputs, with suction filter, Pressure range –100 to 0 kPa

Note 5) The filter included in this product is of an simple type, and will become clogged quickly in environments with high quantities of dust or particulates. Please make additional use of an air suction filter of the ZFA, ZFB or ZFC series.

#### **8** Vacuum switch electrical entry

С	Connector type, with 0.6 m lead wire
CL	Connector type, with 3 m lead wire

## **∆**Warning

The filter case of this suction filter is made of nylon. Contact with alcohol or similar chemicals may cause it to be damaged. Also, do not use the filter when these chemicals are present in the atmosphere.

## 9 Fitting (V port) Note 6)

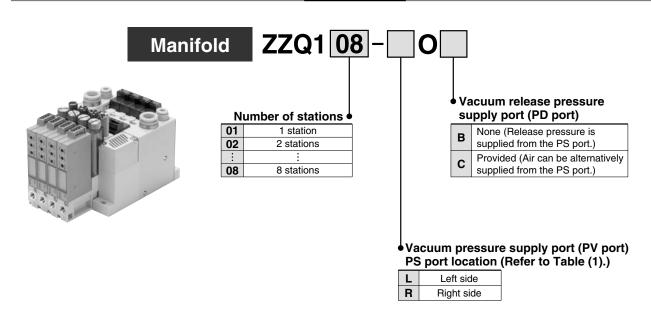
Symbol	Symbol Applicable tubing O.D.		
0 Without fitting (M5 x 0.8)		_	
1 ø3.2 (Straight)		KJS23-M5	
2	ø4 (Straight)	KJS04-M5	
3 ø6 (Straight)		KJS06-M5	
4	ø3.2 (Elbow)	KJL23-M5	
5	ø4 (Elbow)	KJL04-M5	

## 10 Fitting (PS / PV port) Note 6, 7)

Symbol	Symbol Applicable tubing O.D.	
0	Without fitting (M5 x 0.8)	_
2	ø4 (Straight)	KJS04-M5
3	ø6 (Straight)	KJS06-M5
5	ø4 (Elbow)	KJL04-M5

Note 7) Manifold type: Not applicable

#### How to Order

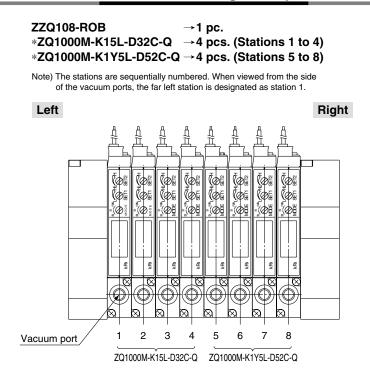


### Table (1) Air Supply Port Location on the Manifold

PD port	Manifold		Left			Right	
PD port	PS port location	PS	PV	PD	PS	PV	PD
в	L (Left side)	_		_	<ul> <li>Note)</li> </ul>	_	_
	R (Right side)	<ul> <li>Note)</li> </ul>	_	_	—		_
С	L (Left side)	_				_	
	R (Right side)	•	_		_		•

Note) The position of each port is shown in terms of its location when vacuum port is in front. Release pressure is supplied from the PS port.

# Manifold Ordering Example



# **Specifications**

## Common

Switching	Switching method for vacuum/release valve Piloted		
Cv factor		0.11	
	Vacuum pressure supply port (PV)	0 to -101.3 kPa	
Supply pressure range	Pilot/Pressure port (PS)	0.3 to 0.5 MPa (Normally open: 0.3 to 0.45 MPa)	
	Supply pressure port for vacuum release (PD)	0.3 to 0.5 MPa (Normally open: 0.3 to 0.45 MPa), and also PD pressure $\leq$ PS pressure	
Operating	perating temperature range 5 to 50°C		

# Weight

Single	With suction filter Note 1)	95 g
unit	With switch and suction filter Note 2)	109 g
	End plate assembly for manifold	122 g

Note 1) Including a 0.3 m connector for the supply valve and vacuum

release valve. Note 2) Including a 0.3 m connector for the supply valve and vacuum release valve and a 0.6 m connector for switch.

○ Calculation of weight for the manifold type (Single unit weight) x (Number of stations) + (Weight of end plate assembly for manifold) Example) Switch + 8 stations with suction filter 109 g x 8 + 122 g = 994 g

### Supply Valve / Vacuum Release Valve

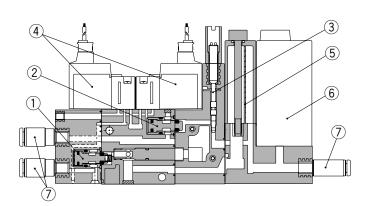
Туре		Normally closed		Latching type	Normally open
Item		Standard (1 W)	Low wattage type (0.5 W)		Normally open
Model (Refer to "How to Order" for solenoid valves on page 31.)		VQ110-□	VQ110Y-□	VQ110 <sup>L</sup> -□	ZQ1-VQ120-□
Fluid			Air / In	ert gas	
Maximum operating	pressure		0.5 MPa		0.45 MPa
Minimum operating	pressure	0.3 MPa			
Ambient and fluid temperature		5 to 50°C			
Lubrication		Not required			
Manual override		Non-locking push type / Locking type (Tool type)		Push-locking type	Non-locking push type / Locking type (Tool type)
Rated coil voltage		12, 24 VDC	12, 24 VDC	12, 24 VDC	12, 24 VDC
Power consumption DC (current value)		1 W	0.5 W	1	w
Electrical entry		Gror	Grommet L-type plug connector Grommet		Grommet
		L-type plug connector (with light	ght/surge voltage suppressor)	(with light/surge voltage suppressor) (with light/surge voltage suppres	

# **Output / Display / Negative Pressure**

Mod	del (Refer to "How to Order" for vacuum pressure switch on page 31.)	ZQ1S-D32□-AS	ZQ1S-D52□-AS	
Rate	ed pressure range	0 to -100 kPa		
Set	pressure range	0 to –{	99 kPa	
Wit	hstand pressure	0.2	MPa	
Flui	id	Air / Non-corrosive/I	Non-combustible gas	
Pov	ver supply voltage	12 to 24 \	/DC ±10%	
Cur	rent consumption	35 mA or less [with power supply voltage of	24 VDC and switch output ON (with no load)]	
Am	bient temperature range	5 to 50 °C (with no free	ezing or condensation)	
Am	bient humidity range	35 to 85 %RH in operation and	I saving (with no condensation)	
Wit	hstand voltage	500 VAC	for 1 min.	
Insu	ulation resistance	50 M $\Omega$ or more (between live parts and pressure port at 500 VDC Mega)		
Swi	tch output	2 NPN outputs	2 PNP outputs	
	Maximum load current	80 mA (per output)		
Maximum applied voltage		30 V (for NPN output)		
	Residual voltage	NPN output: 0.8 V or less (at 80 mA inrush) PNP output: 1.2 V or less (at 80 mA discharge)		
Response time 2 ms or less		or less		
Hys	steresis	0 to 15% F.S. or less (variable)	2% F.S. or less (fixed)	
Dis	play	2-digit Red LED		
Display accuracy		±3 %F.S. ±2 digits		
Output indicator light		Illuminates when the output is turned ON. (Red LED for OUT1 and Green LED for OUT2)		
Ana	alog output	(Only applicable to D31 and D51)		
	Output voltage	1 to 5 V ±2.5	% F.S. or less	
	Linearity	±0.5 F.S. or less		



# Construction



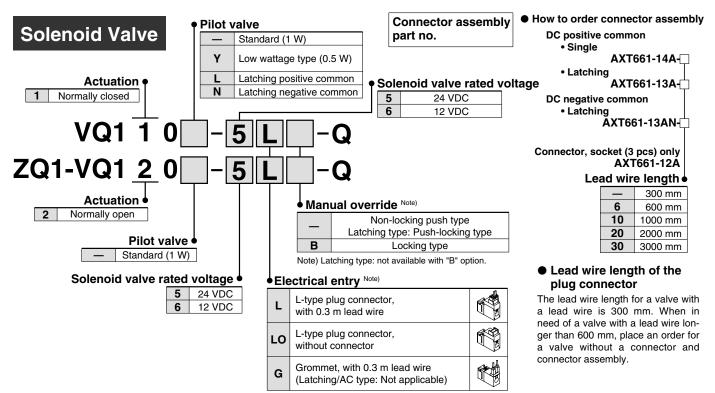
#### **Component Parts**

No.	Description	Material
1	Poppet valve assembly for supply valve	-
2	Poppet valve assembly for vacuum release valve	-
3	Vacuum release flow adjustment needle	Aluminum alloy

#### **Replacement Parts**

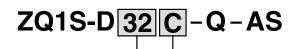
No.	o. Description Material Part no.		Part no.	
4 Solenoid valve		-	Refer to the below.	
5	Filter element	PVF	XT534-5-001-AS	
6 Vacuum pressure switch – Refer to the below.		Refer to the below.		
7	Fitting	-	Refer to "How to Order" below.	

How to Order



Note) Mounting screws are attached.

# Vacuum Pressure Switch



#### Vacuum pressure switch specifications

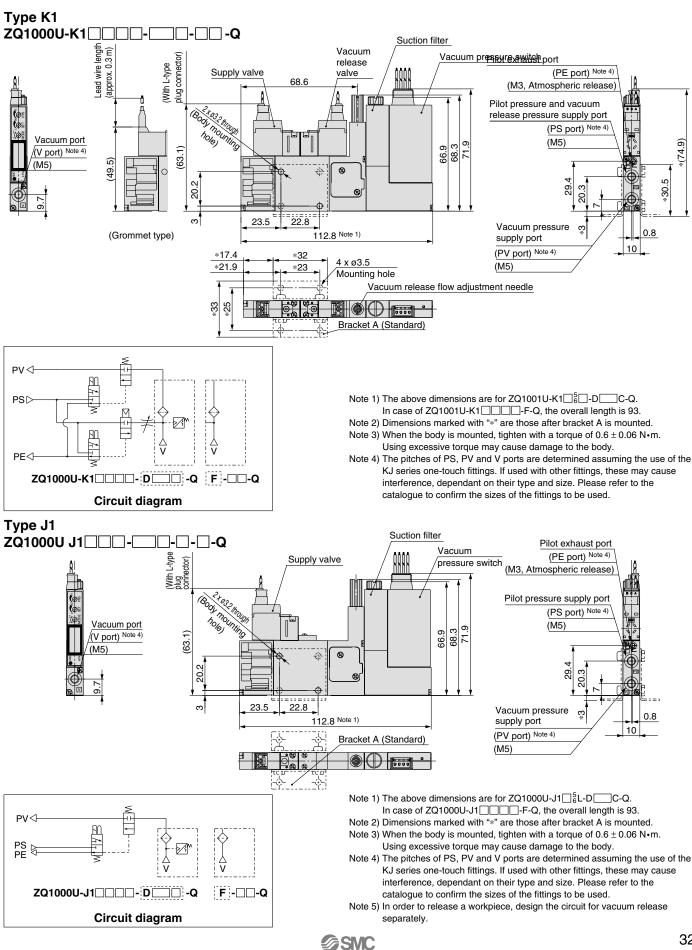
D322 NPN outputs, Pressure range -100 to 0 kPaD522 PNP outputs, Pressure range -100 to 0 kPa

# Electrical entry Note)

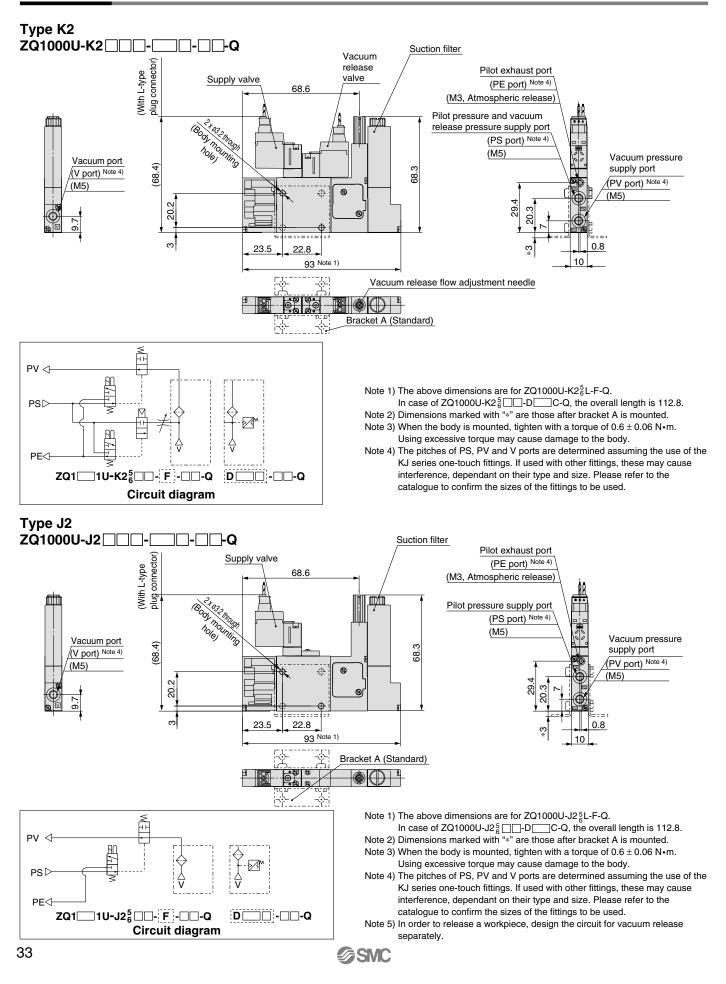
C Connector type, with 0.6 m lead wire CL Connector type, with 3 m lead wire Note) Mounting screws are attached.

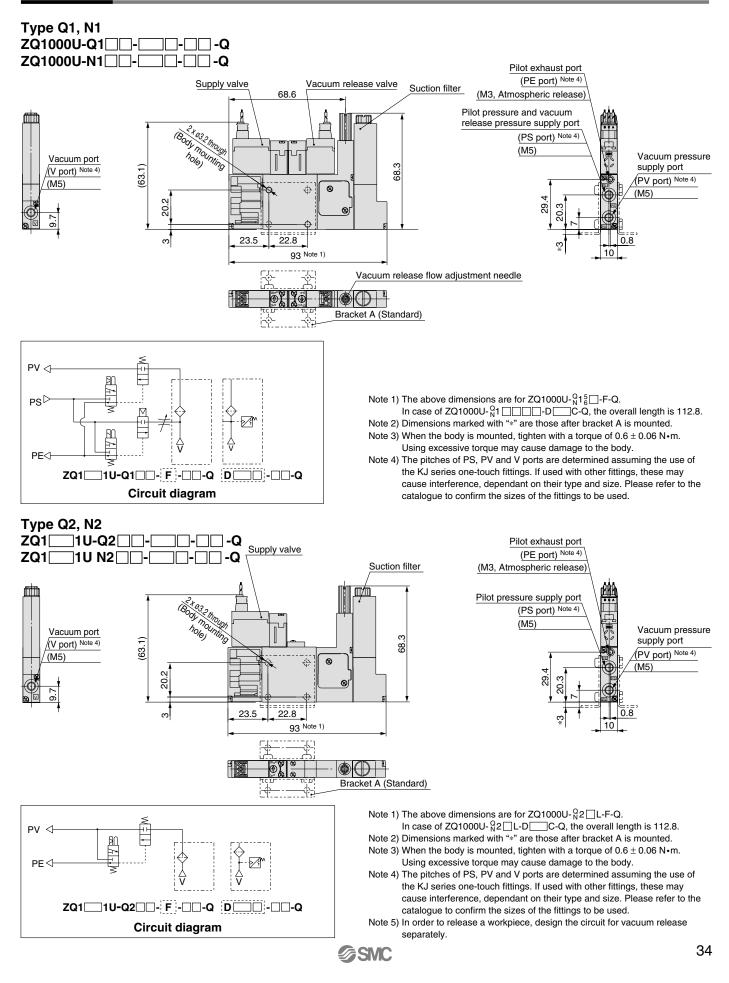
Switch connector part no	э.
ZQ1-AS-003	٦
ZQ1-AS-004	

**SMC** 

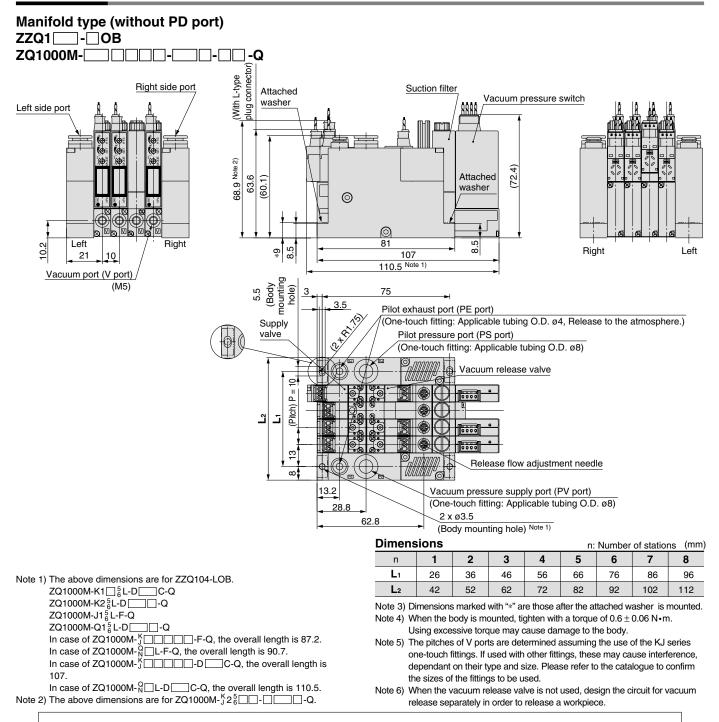


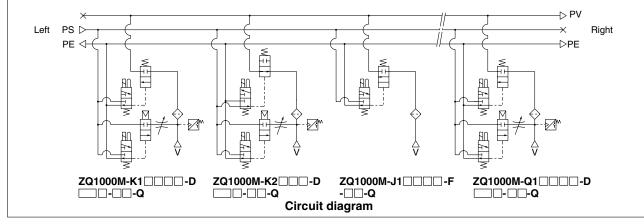
# Series **ZQ**



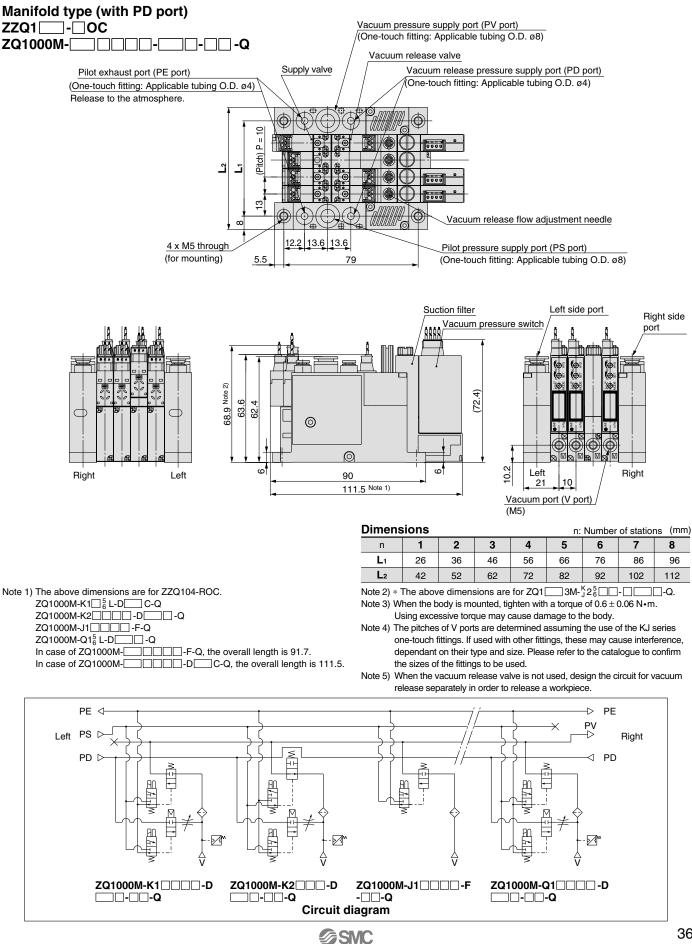








**SMC** 

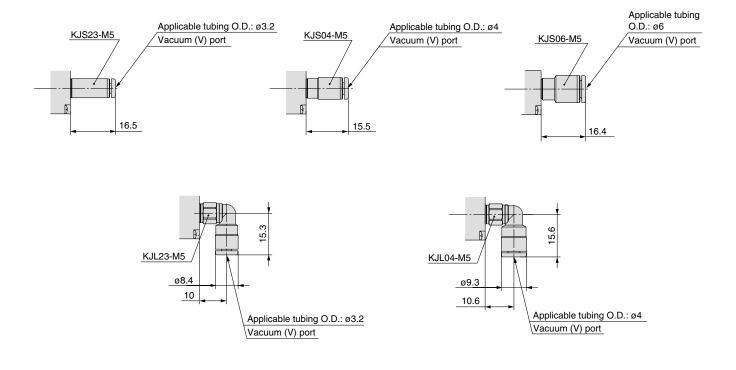




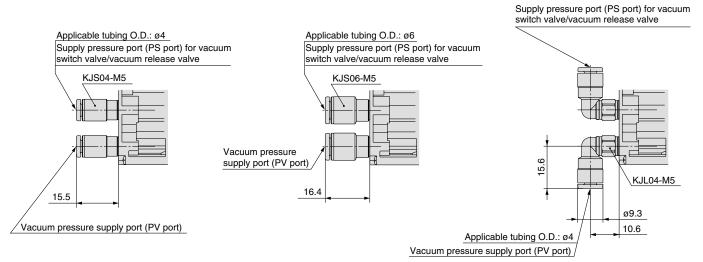
# Fittings / Fitting type filter dimensions after installation

# V port

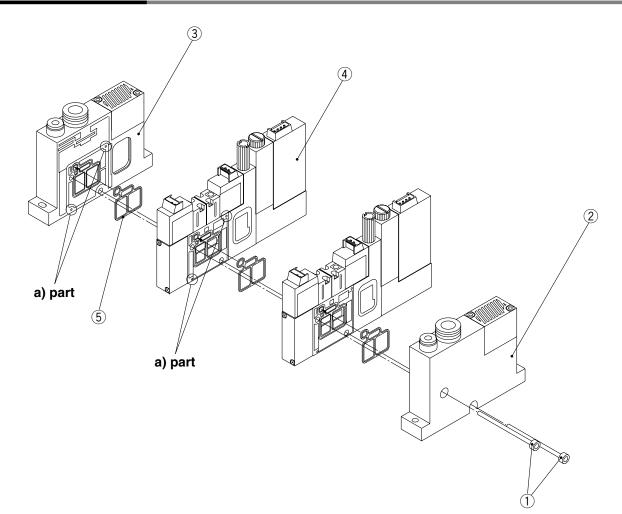
(Suction filter, Vacuum pressure switch)



PS / PV port



# Manifold Exploded View



### **Component Parts**

No.	lo. Description Part no.	
1	Hexagon socket head cap screw	Refer to "How to Order" below.
2	End block L	Refer to "Table (1)".
3 End block R Refer to "Table (2)" (including 1 pc. of (		Refer to "Table (2)" (including 1 pc. of $(5)$ ).
4	4 Vacuum pump system ZQ1000M-□□□-□-Q Note 1) (including 1	
5	Ejector body gasket for manifold	ZQ-3-005-10AS Note 2)

Note 1) Refer to page 27 and 28 for detailed description of "How to Order". Note 2) 10 pcs. are included in one set.

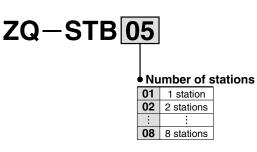
## Table (1) End Block L Part No.

PD port specification PV port location when the V port is viewed in front		Without PD port
Right side	ZQ1L-O-S0C	ZQ1L-O-S0B
Left side	ZQ1L-O-V0C	ZQ1L-O-V0B

#### Table (2) End Block R Part No.

PD port specification PV port location when the V port is viewed in front	With PD port	Without PD port
Right side	ZQ1R-O-V0C	ZQ1R-O-V0B
Left side	ZQ1R-O-S0C	ZQ1R-O-S0B

# How to Order Hexagon Socket Head Cap Screw



Note) 2 pcs. are included in one set.

## **Working Procedure**

#### Disassembly

Loosen and remove the hexagon socket head cap bolts

#### Assembly

- 1. Install the ejector body gasket for manifold (5) into the gasket groove of each ejector assembly (4).
- 2. Install the ejector body gasket for manifold (5) into the gasket groove of the end block R (2).
- 3. Align the ejector assemblies (4), end block (L) (2), and end block (R) (3) using positioning pins (at the two "a" positions) and fasten with a clamp rod (1) (2 pcs.) (with a tightening torque of 0.6 N•m ± 0.06 N•m).

# Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "**Caution**," "**Warning**" or "**Danger**." They are all important notes for safety and must be followed in addition to International Standards<sup>Note 1)</sup> and other safety regulations.

Otariat		
	ISO 4413: Hydra	natic fluid power – General rules relating to systems. ulic fluid power – General rules relating to systems. fety of machinery – Electrical equipment of machines. (Part 1: General requirements)
		pulating industrial robots - Safety.
	Caution:	<b>Caution</b> indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.
<u> </u>	Warning:	<b>Warning</b> indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.
	Danger :	<b>Danger</b> indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.
		<b>A</b> Warning
decid Since decid expe comp catale	ides its specifies the product species of the product species of the person of the performance patibility with the postibility with the postibility with the postibility with the product of the performance of the performanc	of the product is the responsibility of the person who designs the equipment or fications. Excified here is used under various operating conditions, its compatibility with specific equipment must be who designs the equipment or decides its specifications based on necessary analysis and test results. The and safety assurance of the equipment will be the responsibility of the person who has determined its product. This person should also continuously review all specifications of the product referring to its latest with a view to giving due consideration to any possibility of equipment failure when configuring the
2. Only The	y personnel w product specified	<b>ith appropriate training should operate machinery and equipment.</b> here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or ir products must be performed by an operator who is appropriately trained and experienced.
3. Do r	not service or	attempt to remove product and machinery/equipment until safety is confirmed.
1. Th	e inspection and r	maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway have been confirmed.
		to be removed, confirm that the safety measures as mentioned above are implemented and the power from rce is cut, and read and understand the specific product precautions of all relevant products carefully.
3. Be	fore machinery/ec	uipment is restarted, take measures to prevent unexpected operation and malfunction.
		orehand and take special consideration of safety measures if the product is to be
	-	e following conditions.
		ronments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
tre bra	atment, combusti	ment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical on and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and ss applications, safety equipment or other applications unsuitable for the standard specifications described in le.
3. An	application which	could have negative effects on people, property, or animals requiring special safety analysis.
		circuit, which requires the provision of double interlock for possible failure by using a mechanical protective ical checks to confirm proper operation.
Exem	ption from L	iability
		oyees shall be exempted from liability for any loss or damage arising out of earthquakes or fire, action by a third per- perror with or without intention, product misuse, and any other damages caused by abnormal operating conditions.
ge, loss cluding	of profits, or loss	oyees shall be exempted from liability for any direct or indirect loss or damage, including consequential loss or dama- of chance, claims, demands, proceedings, costs, expenses, awards, judgments and any other liability whatsoever in- penses, which may be suffered or incurred, whether in tort (including negligence), contract, breach of statutory duty,
tions ou	utside of the specifi	•
4. SMC is	exempted from liab	ility for any loss or damage whatsoever caused by malfunctions of its products when combined with other devices or





# Series ZQ Specific Product Precautions

For Vacuum Equipment Common Precautions, refer to "Precautions for Handling Pneumatic Devices (M-03-E3A)."

## **Design and Selection**

# **A**Warning

#### 1. Avoid energizing the solenoid valve for long periods of time.

If a solenoid valve is energized for a long period of time, the coil will get hot and the performance may be reduced. Additionally, the peripheral equipment in close proximity may also be badly affected. Use a low wattage solenoid valve when the solenoid valve is energized continuously or when the duration of the energization is longer than the non-energized period each day. Periods of energization can be shortened by using a normally opened or latching type solenoid valve. But, do not energize the coil on both A and B sides simultaneously when using the latching type.

Continuous energization of the solenoid valve should be less than 10 minutes in duration and the energization period should be shorter than the non-energized period. Take measures for any heat radiation so that the temperature is within the range of solenoid valve specifications when the solenoid valve is mounted on the control panel. Please pay special attention to any temperature increases when a manifold type with 3 stations or more is energized continuously or when three individual units are placed in close proximity.

# 2. Use the vacuum equipment within the operating supply pressure range.

When operating with a lower supply pressure, the vacuum performance will be reduced and the poppet valve will cause malfunction.

Never use the vacuum equipment in other than the operating supply pressure range as this may cause damage to the product resulting in potentially dangerous operation.

#### 3. Suspension of operation for long periods of time

Please use caution — as detailed below — when the vacuum equipment is turned off for periods in excess of 6 hours.

• Be sure to turn off the pressure supply to the vacuum equipment.

Please observe this precautions as the supply pressure will be applied for a extra period of time due to the line pressure increase and may result in damage to the vacuum equipment.

• Be sure to turn off the power supply to the solenoid valve and the pressure switch.

Please observe this precautions as any heat generated due to the length of energization time may seriously affect the vacuum equipment and peripheral equipment resulting in potentially dangerous operation.

#### 4. Check valve

The check valve has a function to prevent the exhaust air from the silencer overflowing to the vacuum port side when a manifold is used. However, depending on usage conditions, it does not always suppress air overflow to the desired extent. During usage, please inspect thoroughly with actual machine. Also, no guarantee is therefore provided when used for any other purposes. It is especially dangerous if used for the purpose of workpiece drop prevention in the case of operator blackout. Therefore, please take additional measures for providing drop prevention, such as providing a guide.

#### 5. Exhaust port (EXH port) on the vacuum ejector

Please check the exhaust port (EXH port) on the vacuum ejector, so that any exhaust resistance will not be increased due to insulating materials or restrictions in the piping. The exhaust resistance may reduce the ejector's performance. Additionally, never use this product in an application where the exhaust port is blocked when detaching a workpiece. This misuse may result in possible damage to the product.

# **≜** Warning

#### 6. Vacuum release flow adjustment needle

Adjust the vacuum release flow adjustment needle from the fully closed to the open state by 1/8 to 1/4 turns to detach a workpiece completely during the ON time of a release valve. Do not supply compressed air while the vacuum release flow adjustment needle is adjusted. Securely lock it with a lock nut after adjustment.

#### 7. How to use the latching type solenoid valve

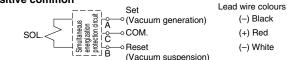
Our Latching type solenoid are fitted with a self-detaining mechanism. Its construction features an armature inside the solenoid which is set or reset using spontaneous energization. (10 ms or greater) Therefore, continuous energization is not required.

## How to Use the Latching Type Plug Connector

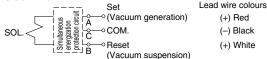
#### Wiring specifications

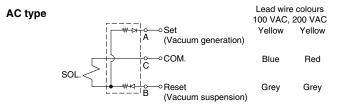
 Wiring should be connected as shown below. Connect with the power supply respectively.

DC positive common



DC negative common





Special care must be taken for the latching type.

- Avoid using this product with a circuit which electrifies both the set and reset signals simultaneously.
- 2. The minimum energization time required for self-detaining is 10 ms.
- Please contact SMC when using this product in locations where there are vibration levels of 30 m/s<sup>2</sup> or above or highly magnetic fields. No problems arise in normal usage or locations.
- 4. This valve retains the reset position (Flow path:  $A \rightarrow R$ ) at the time of shipment. However, it may alter to the set position during transportation or due to vibration when mounting the valve. Therefore, confirm the home position either manually or

#### Mounting

# **A**Warning

1. Screw tightening torque for mounting the body should be performed with 0.6 ± 0.06 N⋅m. Excessive torque may damage the product.





### EUROPEAN SUBSIDIARIES:

# Austria

SMC Pneumatik GmbH (Austria). Girakstrasse 8, A-2100 Korneuburg Phone: +43 2262-622800. Fax: +43 2262-62285 E-mail: office@smc.at http://www.smc.at



SMC Pneumatics N.V./S.A. Nijverheidsstraat 20, B-2160 Wommelgem Phone: +32 (0)3-355-1464, Fax: +32 (0)3-355-1466 E-mail: info@smcpneumatics.be http://www.smcpneumatics.be



#### Bulgaria

SMC Industrial Automation Bulgaria EOOD Business Park Sofia, Building 8 - 6th floor, BG-1715 Sofia Phone:+359 2 9744492, Fax:+359 2 9744519 E-mail: office@smc.bg http://www.smc.bg



#### Croatia SMC Industrijska automatika d.o.o. Cromerec 12, HR-10000 ZAGREB Phone: +385 1 377 66 74, Fax: +385 1 377 66 74 E-mail: office@smc.hr http://www.smc.hr



# Czech Republic

SMC Industrial Automation CZ s.r.o. Hudcova 78a, CZ-61200 Brno Phone: +420 5 414 24611, Fax: +420 5 412 18034 E-mail: office@smc.cz http://www.smc.cz



#### Denmark SMC Pneumatik A/S

Egeskovvej 1, DK-8700 Horsens Phone: +45 70252900, Fax: +45 70252901 E-mail: smc@smcdk.com http://www.smcdk.com



# Estonia SMC Pneumatics Estonia OÜ

Laki 12, 106 21 Tallinn Phone: +372 6510370, Fax: +372 65110371 E-mail: smc@smcpneumatics.ee http://www.smcpneumatics.ee

# Finland

SMC Pneumatics Finland Oy PL72, Tiistinniityntie 4, SF-02231 ESPOO Phone: +358 207 513513, Fax: +358 207 513595 E-mail: smcfi@smc.fi http://www.smc.fi



SMC Pneumatique, S.A. 1, Boulevard de Strasbourg, Parc Gustave Eiffel Bussy Saint Georges F-77607 Mame La Vallee Cedex 3 Phone: +33 (0)1-6476 1000, Fax: +33 (0)1-6476 1010 E-mail: contact@smc-france.fr http://www.smc-france.fr



SMC Pneumatik GmbH Boschring 13-15, D-63329 Egelsbach Phone: +49 (0)6103-4020, Fax: +49 (0)6103-402139 E-mail: info@smc-pneumatik.de http://www.smc-pneumatik.de



#### Greece

SMC Hellas EPE Anagenniseos 7-9 - P.C. 14342. N. Philadelphia, Athens Phone: +30-210-2717265, Fax: +30-210-2717766 E-mail: sales@smchellas.gr http://www.smchellas.gr



Hungary SMC Hungary Ipari Automatizálási Kft. Torbágy út 19, H-2045 Törökbálint Phone: +36 23 511 390, Fax: +36 23 511 391 E-mail: office@smc.hu http://www.smc.hu



SMC Pneumatics (Ireland) Ltd. 2002 Citywest Business Campus, Naas Road, Saggart, Co. Dublin Phone: +353 (0)1-403 9000, Fax: +353 (0)1-464-0500 E-mail: sales@smcpneumatics.ie http://www.smcpneumatics.ie



SMC Italia S.p.A Via Garibaldi 62, I-20061 Carugate, (Milano) Phone: +39 (0)2-92711, Fax: +39 (0)2-9271365 E-mail: mailbox@smcitalia.it http://www.smcitalia.it



Latvia SMC Pneumatics Latvia SIA Dzelzavas str. 120g, Riga LV-1021, LATVIA Phone: +371 67817700, Fax: +371 67817701 E-mail: info@smclv.lv http://www.smclv.lv



Oslo g.1, LT-04123 Vilnius







SMC Pneumatics Norway A/S Vollsveien 13 C, Granfos Næringspark N-1366 Lysaker Tel: +47 67 12 90 20, Fax: +47 67 12 90 21 E-mail: post@smc-norge.no http://www.smc-norge.no



SMC Industrial Automation Polska Sp.z.o.o. ul. Poloneza 89, PL-02-826 Warszawa, Phone: +48 22 211 9600, Fax: +48 22 211 9617 E-mail: office@smc.pl http://www.smc.pl



Portugal SMC Sucursal Portugal, S.A. Rua de Eng<sup>o</sup> Ferreira Dias 452, 4100-246 Porto Phone: +351 226 166 570, Fax: +351 226 166 589 E-mail: postpt@smc.smces.es http://www.smc.eu



SMC Romania srl Str Frunzei 29, Sector 2, Bucharest Phone: +40 213205111, Fax: +40 213261489 E-mail: smcromania@smcromania.ro http://www.smcromania.ro

# Russia

SMC Pneumatik LLC. 4B Sverdlovskaja nab, St. Petersburg 195009 Phone.:+7 812 718 5445, Fax:+7 812 718 5449 E-mail: info@smc-pneumatik.ru http://www.smc-pneumatik.ru



Slovakia SMC Priemyselná Automatizáciá, s.r.o. Fatranská 1223, 01301 Teplicka Nad Váhom Phone: +421 41 3213212 - 6 Fax: +421 41 3213210 E-mail: office@smc.sk http://www.smc.sk



Slovenia SMC industrijska Avtomatika d.o.o. Mirnska cesta 7, SI-8210 Trebnje Phone: +386 7 3885412 Fax: +386 7 3885435 E-mail: office@smc.si http://www.smc.si



Spain SMC España, S.A. Zuazobidea 14, 01015 Vitoria Phone: +34 945-184 100, Fax: +34 945-184 124 E-mail: post@smc.smces.es http://www.smc.eu



Sweden SMC Pneumatics Sweden AB Ekhagsvägen 29-31, S-141 71 Huddinge Phone: +46 (0)8-603 12 00, Fax: +46 (0)8-603 12 90 E-mail: post@smcpneumatics.se http://www.smc.nu



# Switzerland

SMC Pneumatik AG Dorfstrasse 7, CH-8484 Weisslingen Phone: +41 (0)52-396-3131, Fax: +41 (0)52-396-3191 E-mail: info@smc.ch http://www.smc.ch



# Entek Pnömatik San. ve Tic. A\*. Perpa Ticaret Merkezi B Blok Kat:11 No: 1625, TR-34386, Okmeydani, Islanbul Phone: +90 (0)212-444-0762, Fax: +90 (0)212-221-1519 E-mail: smc@entek.com.tr http://www.entek.com.tr



SMC Pneumatics (UK) Ltd Vincent Avenue, Crownhill, Milton Keynes, MK8 0AN Phone: +44 (0)800 1382930 Fax: +44 (0)1908-555064 E-mail: sales@smcpneumatics.co.uk http://www.smcpneumatics.co.uk



Phone: +370 5 264 81 26 Eax: +370 5 264 81 26



ARGENTINA, AUSTRALIA, BOLIVIA, BRASIL, CANADA, CHILE, CHINA, HONG KONG, INDIA, INDONESIA, MALAYSIA, MEXICO, NEW ZEALAND, PHILIPPINES, SINGAPORE, SOUTH KOREA, TAIWAN, THAILAND, USA, VENEZUELA

> http://www.smc.eu http://www.smcworld.com

